DEPARTMENT OF MECHANICAL ENGINEERING

SCHEME OF INSTRUCTION AND SYLLABI OF

M.E.

(Mechanical Engineering)

Specialization:

CAD/CAM



2016-17 - CBCS

CHAITANYA BHARATHI INSTITUTE OF TECHNOLOGY
(Autonomous)

Affiliated to Osmania University

Hyderabad – 500 075, Telangana, INDIA

CHAITANYA BHARATHI INSTIUTE OF TECHNOLOGY

(AUTONOMOUS)-CBCS

Gandipet, Hyderabad – 500 075

INSTITUTE

Vision

To be a centre of excellence in technical education and research

Mission

To address the emerging needs through quality technical education and advanced research

DEPARTMENT

Vision

To be a Pace Setter in the field of mechanical Engineering by providing conducive environment for understanding and applying its principles to cater the needs of Society

Mission

To impart quality & innovative technical education to the students of mechanical engineering for their professional achievements in consultancy, R&D and to become successful entrepreneur enabling them to serve the society in general and the industry in particular

CHAITANYA BHARATHI INSTIUTE OF TECHNOLOGY

(AUTONOMOUS)

Gandipet, Hyderabad – 500 075

MECHANICAL ENGINEERING

Programme: M.E (CAD/CAM)

Programme Educational Objectives:

- 1. Will become professional contributors in the industry related to the area of CAD/CAM
- 2. Will excel in research & development and consultancy
- 3. Will become entrepreneurs in CAD/CAM industry.

POs describe what students are expected to know or be able to do by the time of graduation from the program.

- 1. To demonstrate knowledge in core subjects of CAD/CAM with mathematical & numerical orientation.
- 2. To exhibit proficiency in usage of software packages of solid modeling, meshing and analysis.
- 3. To understand advanced technologies in the area of Manufacturing & Automation in Manufacturing
- 4. To posses the necessary skills to prepare the project proposals by referring technical papers in various reputed journals, pertaining to CAD/CAM.
- 5. To Understand the concepts and principles of Engineering Research Methodology and apply the same for designing and conducting experiments related to the area of CAD/CAM.
- 6. To acquire leadership qualities by organizing and participating in various events.

Note: PEOS are expected to achieve after 2 years of graduation

Scheme of Instruction & Examination M.E. (CAD/CAM) – Mechanical Engineering - 4 Semesters (Full Time)

	IVI.E. (CAD/C/	nivi) – iviecii	allical E	Semester - I	4 Semesters	(i uli i illie)			
		No. of Hr	s. per	Duration		Marks for			
SI.		week	o. po.	(Hrs)	Internal		Total		
No	Subject	Lecture	T/P/S	1	Assessment	End Exam	Marks	Credits	
1.	Core	3	1	4	30	70	100	4	
2.	Core	3	1	4	30	70	100	4	
3.	Core	3	1	4	30	70	100	4	
4.	Elective	3		3	30	70	100	3	
5.	Elective	3		3	30	70	100	3	
6.	Elective	3		3	30	70	100	3	
7.	Laboratory		3	3	50		50	2	
8.	Seminar - I		3	3	50		50	2	
9.	Soft Skills								
	Total	18	09		340	360	700	25	
	•			Semester - II					
		No. of Hr	s. per		Mark	s for			
		week		Duration	Internal		Total		
SI.				(Hrs)	Assessment	End Exam	Marks	Credits	
No	Subject	Lecture	T/P/S	-/-					
1.	Core	3	1		30	70	100	4	
2.	Core	3	1		30	70	100	4	
3.	Core	3	1		30	70	100	4	
4.	Elective	3			30	70	100	3	
5.	Elective	3	-		30	70	100	3	
6.	Elective	3			30	70	100	3	
7.	Laboratory - II		3		50		50	2	
8.	Seminar - II		3		50		50	2	
9.	Mini Project		2		50		50	1	
	Total	18	11		390	360	750	26	
				Semester - III					
					ks for				
SI.	Subj	iect		Internal	K3 IOI	Total Ma	arke	Credits	
No	Oubj	COL		Assessment	End Exam	1 Otal Mic	ai N3		
	Project Seminar*			ASSESSITION					
	(i)Problem formulation	and submis	sion of						
	synopsis within 8 weel		01011 01						
_	commencement of 3 rd	Semester.							
1	(50 Marks)			100	-	100		6	
	(ii) Preliminary work or	n Project							
	implementation.								
	(50 Marks)								
	Total			100		100		6	
			- ;	Semester - IV					
SI.			Mar	ks for			Credits		
Si. No	Subj	ect		Internal	End Exam	Total Ma	arks	Creaits	
INO		2,50.			Enu Exam				
1	Project Work			100	100	200		12	

Note: Six core subjects, Six elective subjects, Two Laboratory Courses and Two Seminars, Mini Project

and Soft Skills should normally be completed by the end of semester II.

and 50 marks by the internal committee

Credit requirements for the award of degree, lower limit and upper limit of credits for registration by a student in a semester Credit Requirement for the award of M.E/M. Tech. Degree is 69

^{*} Project seminar presentation on the topic of Dissertation only, 50 marks awarded by the project guide

Scheme of Instruction & Examination Post Graduate course in Mechanical Engineering

with specialization in CAD/CAM

Course duration: 4 Semesters (Full - Time)

				me of	Schem	e of Exa	mination	Credits
SI.	Syllabus			s per		I		
No	Ref.No.	Subject		-	Duration	Ма	x. Marks	
			we	ek	in Hours	End		
			L	T/P	III Hours		Internal Assessment	
		CORE SUBJECTS		•				
1.	16MEC101	Automation	3	1	4	70	30	4
2.	16MEC102	Computer Aided Modeling and Design	3	1	4	70	30	4
3.	16MEC103	Computer Integrated Manufacturing	3	1	4	70	30	4
4.	16MEC104	Computer Aided Mechanical Design and Analysis	3	1	4	70	30	4
5.	16MEC105	Finite Element Techniques	3	1	4	70	30	4
6.	16MEC205	Computational Fluid Dynamics	3	1	4	70	30	4
		ELECTIVES						
1	16MEE101	Failure Analysis and Design	3		3	70	30	3
2.		Integrated Mechanical Design	3	Ţ	3	70	30	3
3.		Robotic Engineering	3		3	70	30	3
4.		Programming Methodology and Data Structures	3	-	3	70	30	3
5.	16MEE105	Optimization Techniques	3)	3	70	40	3
6.		Vibrations Analysis and Condition Monitoring	3		3	70	30	3
7.		Engineering Research Methodology	3		3	70	30	3
8.		Tribology In Design	3		3	70	30	3
9.		Advanced Mechanics of Materials	3		3	70	30	3
10.	16MEE110	Mechanics of Composite Materials	3		3	70	30	3
11.		Theory of Elasticity and Plasticity	3		3	70	30	3
12.		Experimental Techniques and Data Analysis	3		3	70	30	3
13.		Design for Manufacture	3		3	70	30	3
14. 15.		Data Base Management Systems Fracture Mechanics	3		3 3	70 70	30 30	3 3
16.		Design of Press Tools	3		3	70	30	3
17.		Design of Dies	3		3	70	30	3
18.		Rapid Prototyping Principles & Applications	3		3	70	30	3
19.		Flexible Manufacturing Systems	3		3	70	30	3
20.		Non-Traditional Machining & Forming	3		3	70	30	3
21	16MEE121	Product Design and Process Planning	3		3	70	30	3
		DEPARTMENTAL I	REQU	REME	NTS	1		
1.	16MEC106	CAD/CAM Lab (Lab –I)	 	3			50	2
2.	16MEC107	Computation Lab (Lab –II)		3			50	2
3.	16MEC108	Seminar – I		3			50	2
4.	16MEC109	Seminar – II		3			50	2
5	16MEC110	Mini Project		2			50	1
6	16MEC111	Project Seminar		6			100	6
7	16MEC112	Project work		6		100	100	12

CBIT	Autonomous Regulation		Semester-1 AY - 2006-17						
Department	Mechanical Engineering	Progr		ode & Na	ame	ME CA	AD/CAM	0-17	
Course Code	Course Name		s/ Week	000 0 140	Credit		m Marks		
	Course Harris	I	T	Р	C	F	I	Total	
16MEC 101	AUTOMATION	3	1	0	4	70	30	100	
Objective (s)	Student will								
	 To learn & understan industries To understand Detroit To conceptualize & de To learn about automs To understand different To design effective an 	type a esign as ated ma nt autor	utomatio sembly l aterial ha nated st	n & flow line balan andling sy orage/ret	lines. icing /stems rieval syst	tem	ficance in	manufacturing	
Outcome (s)	Ability to conceptualize Ability to implement lin Ability to understand operations Ability to design, imple Ability to understand operations Ability to design imple	e and d ne balar and de ement a and de	esign au ncing co velop au and use a velop au	tomated ncepts in atomated and appropriate and appropriate atomated	flow lines productio material opriate au material	n and ass handling s tomated in handling s	system sunspection system su	itable for plant facility itable for plant	

Ability to design, implement and use and appropriate automated inspection facility

 Total Hrs 9

Introduction: Definition of automation Types of production Eugetians of Manufacturing Organization and

Introduction: Definition of automation, Types of production, Functions of Manufacturing, Organization and Information Processing in Manufacturing, Production concepts and Mathematical Models, Automation Strategies, Production Economics: Methods of Evaluating Investment Alternatives, Costs in Manufacturing, Break-Even Analysis, Unit cost of production, Cost of Manufacturing Lead time and Work-in-process.

2. Total Hrs 9

Detroit-Type Automation: Automated Flow lines, Methods of Workpart Transport, Transfer Mechanism, Buffer Storage, Control Functions, Automation for Machining Operations, Design and Fabrication Considerations. Analysis of Automated Flow Lines: General Terminology and Analysis, Analysis of Transfer Lines Without Storage, Partial Automation, Automated Flow Lines with Storage Buffers, Computer Simulation of Automated Flow Lines

3. Total Hrs 9

Assembly Systems and Line Balancing: The Assembly Process, Assembly Systems, Manual Assembly Lines, The Line Balancing Problem, Methods of Line Balancing, Computerized Line Balancing Methods, Other ways to improve the Line Balancing, Flexible Manual Assembly Lines. Automated Assembly Systems: Design for Automated Assembly, Types of Automated Assembly Systems, Part Feeding Devices, Analysis of Multi-station Assembly Machines, Analysis of a Single Station Assembly Machine

4. Total Hrs 9

Automated Materials Handling: The material handling function, Types of Material Handling Equipment, Analysis for Material Handling Systems, Design of the System, Conveyor Systems, Automated Guided Vehicle Systems. Automated Storage Systems: Storage System Performance, Automated Storage/Retrieval Systems, Carousel Storage Systems, Work-in-process Storage, Interfacing Handling and Storage with Manufacturing

5. Total Hrs 9

Automated Inspection and Testing: Inspection and testing, Statistical Quality Control, Automated Inspection Principles and Methods, Sensor Technologies for Automated Inspection, Coordinate Measuring Machines, Other Contact Inspection Methods, Machine Vision, Other optical Inspection Methods. Modeling Automated Manufacturing Systems: Role of Performance Modeling, Performance Measures, Performance Modeling Tools: Simulation Models, Analytical Models. The Future Automated Factory: Trends in Manufacturing, The Future Automated Factory, Human Workers in the Future Automated Factory, The social impact

Total hours to be taught 45

Text book (s)

- Mikell P.Grover, Automation, Production Systems and Computer Integrated Manufacturing, Pearson Education Asia
- Education Asia.

 C.Ray Asfahl, Robots and manufacturing Automation, John Wiley and Sons New York.

References:

- 1. N.Viswanadham and Y.Narahari, Performance Modeling of Automated Manufacturing Systems, Printice Hall India Pvt. Ltd.,
- 2. Stephen J. Derby, Design of Automatic Machinary, Special Indian Edition, Marcel Decker, New York Yesdee publishing Pvt. Ltd, Chennai.

CBIT	Autonomous Regulation	on Semester-1 AY - 2006-17							
Department	Mechanical Engineering	Progra		ode & Na	ame		M.E. CAD		
Course Code	Course Name		/ Week	00.0 0	Credit	Maximu	ım Marks	, , ,	
16MEC 102	COMPUTER AIDED	L	Т	Р	С	Е	ı	To	tal
	MODELING AND DESIGN	3	1	0	4	70	30	10	00
Objective (s) Outcome (s)	Student will Understand the 1. Understand the basics o 2. To impart knowledge on 3. Recognize and explain t 4. Understand and apply va 5. Understand various adva Students are able to 1. apply design concepts standards	design he uses arious G anced m	orocess of wirefra eometric odeling c	ame and s transformation	ations		odels throu	gh the g	raphics
	implement Various trans recognize various wiref apply surface modeling t differentiate various soli apply various advanced objects	rame en echniqu d model	tities and es for the ing techn	model the generating	em	parts and i		between	mating
1.							Total	Hrs	9
	ection of cad workstations, Sh						metric mo	deling ,	
Entities, 2d and Geometric Tran Coordinates, R Windowing - Vid Graphics standa	action of cad workstations, Sn 3d primitives, Computer Aided ensformations: 2d Translation, otation and Scaling about arbitra ew ports -Clipping transformationards: GKS, IGES, PDES and the	Design Scaling ary poir ns	, Iterativ , Rotati nts , 3D t	e Design on, Refle	,CAD pro ection an	cess	ng, Homo	geneous	;
Entities, 2d and Geometric Tran Coordinates, R Windowing - Vid Graphics stands 2.	3d primitives, Computer Aided nsformations: 2d Translation, otation and Scaling about arbitrates ports -Clipping transformationards: GKS, IGES, PDES and the second	Design Scaling ary poir ns neir rele	, Iterativ , Rotati nts , 3D t	e Design on, Refle	,CAD pro ection an	cess		geneous	,
Entities, 2d and Geometric Tra Coordinates, R Windowing - Vie Graphics stands 2. Analytic curves Synthetic curves	3d primitives, Computer Aided nsformations: 2d Translation, otation and Scaling about arbitrate worts -Clipping transformationards: GKS, IGES, PDES and the Lines, Circles, Ellipse, Conics. Ses – Cubic, Bezier, B-Splines, Ni	Design Scaling ary poir ns neir rele URBS.	, Iterativ , Rotati nts , 3D t evance Curve M	e Design on, Refle ransform	,CAD pro ection an ations	cess	ng, Homo	geneous	;
Entities, 2d and Geometric Tra Coordinates, R Windowing - Vie Graphics stands 2. Analytic curves Synthetic curves	3d primitives, Computer Aided nsformations: 2d Translation, otation and Scaling about arbitrate ports -Clipping transformationards: GKS, IGES, PDES and the Lines, Circles, Ellipse, Conics.	Design Scaling ary poir ns neir rele URBS.	, Iterativ , Rotati nts , 3D t evance Curve M	e Design on, Refle ransform	,CAD pro ection an ations	cess	ng, Homog	geneous	;
Entities, 2d and Geometric Tran Coordinates, R Windowing - Vio Graphics stands 2. Analytic curves Synthetic curves Wireframe Mod 3. Analytic Surface	3d primitives, Computer Aided Insformations: 2d Translation, otation and Scaling about arbitration arbitration arbitration ards: GKS, IGES, PDES and the Lines, Circles, Ellipse, Conics. In Ellipse, Conics.	Design Scaling ary poir ns neir rele URBS. nitation	, Iterativ , Rotati nts , 3D t evance Curve Ms ace of Re	e Design on, Refle ransform anipulation	,CAD projection an ations	ocess d shearin	Total	Hrs Hrs	9
Entities, 2d and Geometric Tran Coordinates, R Windowing - Vio Graphics stands 2. Analytic curves Synthetic curves Wireframe Mod 3. Analytic Surface	3d primitives, Computer Aided insformations: 2d Translation, otation and Scaling about arbitrates ports -Clipping transformationards: GKS, IGES, PDES and the Lines, Circles, Ellipse, Conics. is – Cubic, Bezier, B-Splines, Nigeling and its advantages and Lines.	Design Scaling ary poir ns neir rele URBS. nitation	, Iterativ , Rotati nts , 3D t evance Curve Ms ace of Re	e Design on, Refle ransform anipulation	,CAD projection an ations	ocess d shearir	Total	Hrs Hrs	9
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Entities, 2d and Geometric Trancoordinates, R. Windowing - Vie Graphics stands 2. Analytic curves Synthetic curves Wireframe Mod 3. Analytic Surface Synthetic Surface Synth	3d primitives, Computer Aided Insformations: 2d Translation, otation and Scaling about arbitration and Scaling about arbitration and Scaling about arbitration ards: GKS, IGES, PDES and the state of th	Design Scaling ary poir ns neir rele URBS. nitation e, Surfa ons ,Su e Solid s, Cell I	, Iterative, Rotation of the vance Curve Management of Registration of the vance of the vance of the vance of the vance of Registration of the vance of	e Design on, Refle ransform anipulation ry (CSG) osition & gn and T	CAD projection an ations Tabulate ns , Surfa Modeling Spatial –	d Cylinde ce Model Occupandesign, P	Total Total Total Total Total Cy Enume Total arametric a	Hrs iques Hrs ration Hrs	9 9

- 1. Ibrahim Zeid, —CAD/CAM, Theory and Practicell, Mc Graw Hill, 1998
- 2. Foley, Van Dam, Feiner and Hughes, —Computer Graphics Principles and Practicell, 2nd Ed., Addison Wesley, 2000

- E. Micheal, —Geometric Modellingll, John Wiley & Sons, 1995
 Hill Jr, F.S., —Computer Graphics using open GLll, Pearson Education, 2003

CBIT	Autonomous Regulation	Semester-1 AY - 2006-17						06-17	
Department	Mechanical Engineering	Progra	amme C	ode & Na	ıme		M.E. CAD	D/CAM	
Course Code	Course Name	Hours	/Week		Credit	Maximu	m Marks		
16MEC 103	COMPUTER INTEGRATED	L	Т	Р	С	Ε		Total	
	MANUFACTURING	3	1	0	4	70	30	100	
Objective (s)	 To identify the main e 	lements	in comp	outer integ	grated ma	nufacturi	ng system	S	
	To use computer in t	he area	of man	ufacturing	g to reduc	duce manual processing and linking			
	computers to all the	the manufacturing machines and increase the productivity, reduce the						ity, reduce the	
	unnecessary costs.								
	To study about comp								
	4. To obtain an overview								
	collection, networks,	machine	e contro	l, as they	apply to	factory r	nanageme	ent and factory	
	floor operation	4: 4		_4	-41141 14		lata avada		
Out = = (=)	5. To describe the integr		manuta	cturing ac	ctivities ini	o a comp	nete syste	m	
Outcome (s)	Student are able to understan 1. the basic of CIM. Co		t ongine	orina oc	mmunico	tion moti	iv produc	et dovolonment	
	 the basic of CIM, Co cycle, collaborative p 		_	•	mmunica	uon mau	ix, produc	t development	
	2. to create the manufac				a and retri	eve data	from data	hasa	
	3. the product design, d	_							
	of computer aided pro	-		aotarabili	ly and acc	Jigir ioi a	occiniony o	onocpio, types	
	4. the CIM technologie		_	ular man	ufacturing	shop-fl	oor contro	ol and flexible	
	manufacturing system					,, 55			
	5. the importance of p		s of ne	tworking,	topology	, networ	k devices	s, selection of	
	network technology, o					•		•	
	6. to apply the concepts				igile & we	b based r	manufactu	ring to product	
	life cycle and process	plan du	iring the	developr	nent of a p	oroduct.			

1. Total Hrs 9

The meaning of Manufacturing Types of Manufacturing: Basic Concepts of CIM: CIM Definition, Elements of CIM, CIM wheel, concept or technology, Evolution of CIM, Benefits of CIM, Needs of CIM: Hardware and

software. Fundamentals of Communication: Communications Matrix. Product Development Cycle, Concurrent Engineering: Definition, Sequential Engineering Versus Concurrent Engineering, Benefits of Concurrent Engineering, Characteristics of concurrent Engineering, Framework for integration of Life-cycle phases in CE, Concurrent Engineering Techniques, Integrated Product Development(IPD), Product Life-Cycle Management

(PLM), Collaborative Product Development

2. Total Hrs 9

Introduction, Manufacturing Data: Types, sources; Database Terminology, Database requirements, Database models, Database Management System, DBMS Architecture, Query Language, Structural Query Language (SQL): Basic structure, Data definition Language (Create, Alter, Drop, Truncate, View), Data Manipulation Language (store, retrieve, update, delete). Illustration of Creating and Manipulating a Manufacturing Database. SQL as a Knowledge Base Query Language. Features of commercial DBMS: Oracle, MySQL, SQL Access, Sybase, DB2. Product Data Management (PDM), Advantages of PDM.

3. Total Hrs 9

Product Design: Needs of the market, Design and Engineering, The design Process, Design for Manufacturability (DFM): Component Design, Design for Assembly. Computer-Aided Process Planning: Basic Steps in developing a process plan, Variant and Generative Process Planning, Feature Recognition in Computer-Aided Process Planning. Material Requirements Planning (MRP), Manufacturing Resource Planning (MRP –II), Cellular Manufacturing: Design of Cellular Manufacturing Systems, Cell Formation Approaches: Machine—Component Group Analysis, Similarity Coefficients-Based Approaches. Evaluation of Cell Design. Shop-floor Control: Data Logging and Acquisition, Automated Data Collection, Programmable Logic Controllers, Sensor Technology. Flexible Manufacturing Systems: Physical Components of an FMS. Types of Flexibility, Layout Considerations: Linear Single Machine Layout, Circular Machine Layout, Cluster Machine Layout, Loop Layout; Operational Problems of FMS. FMS benefits

4. Total Hrs 9

Introduction to Networking, Principles of Networking, Network Terminology, Types of Networks: LAN, MAN, WAN; Selection of Network Technology: Communication medium, Network Topology, Medium access control Methods, Signaling methods; Network Architectures and Protocols: OSI Model, MAP & TOP, TCP/IP, Network Interconnection and Devices, Network Performance. Framework for Enterprise-wide Integration.

CIM Models: ESPRIT-CIM OSA Model, NIST-AMRF Model, Siemens Model of CIM, Digital Equipment Corporation Model, IBM Concept of CIM

5.	Total Hrs	9
Lean Manufacturing: Definition, Principles of Lean Manufacturing, Characteristics of Lean Ma	nufacturing, Va	alue of
Product, Continuous Improvement, Focus on Waste, Relationship of Waste to Profit, Fou	r Functions of	f Lean
Production, Performance Measures, The Supply Chain, Benefits of Lean Manufacturing. Intro	duction to Ag	ile and
Web Based Manufacturing systems.		
Total hours to be taught		45

Text book (s)

- S.Kant Vajpayee: Principles of Computer Integrated Manufacturing, Printice-Hall India
 Singh: Systems Approach to Computer Integrated Design and Manufacturing- John Wiley

- 1. P.Radhakrishnan, S.Subramanyam: CAD/CAM/CIM, New Age International
 2. Alavudeen, Venkateshwaran: Computer Integrated Manufacturing, Printice-Hall India

CBIT	Autonomous Regulation		Sem	ester-1			AY - 200	6-17	
Department	Mechanical Engineering			ode & Na	ame		M.E. CAD	D/CAM	
Course Code	Course Name	Hours	/ Week		Credit	Maximu	m Marks		
16MEC 104	COMPUTER AIDED	L	Т	Р	С	Е	1	To	tal
	MECHANICAL DESIGN AND ANALYSIS	3	1	0	4	70	30		00
Objective (s)	To develop the neces								
	To achieve fundamen			ng of the	theory of	bending (of flat plate	es with v	/arious
	loading and boundary								
		3. To Understand design principles of a component and structures using fracture mechanics							
	approaches								
	4. To enable the importa	able the importance of vibrations in mechanical design and to understand the basic							
	5. To understand the diff		node ext	raction m	ethods in	vibrations			
	6. To understand the full							ımic ana	lysis
Outcome (s)	1. Ability to apply know								
	stresses & strains in p								
	Demonstrate the abil	ity to ic	dentify, f	ormulate	and solv	e probler	ns for a g	given fla	t plate
	bending applications								
	3. An ability to design a	a syster	m or a o	compone	nt to mee	t the de	sired nee	eds of f	racture
	mechanics						l :		
	 Students are able to u Students will understa 								
	6. Student will understa							•	
	analysis problems	iliu liui	ilelicai i	Hethous	iii soiviii	y illulu u	egiee iie	suoiii u	/Hallic
1.	Total Hrs 9								
	Design of pressure Vessels: Introduction and constructional features of pressure vessels, stresses in								
	pressure vessels, shrink fit stresses in built up cylinders, auto frettage of thick cylinders, thermal stresses								
and their signif	ficance.								
2.									
Stresses in fla	Stresses in flat plates: Introduction, Bending of plate in one direction, Bending of plate in two perpendicular								

directions, Thermal stresses in plates, Bending of circular plates of constant thickness, Bending of uniformly

loaded plates of constant thickness

Total Hrs 3.

Fracture Mechanics: Introduction, Modes of fracture failure Griffith Analysis, Energy release rate, Energy release rate of DCB specimen; Stress Intensity Factor; SIF's for edge and centre line crack, Fracture toughness, Elastic plastic analysis through J-integral method: Relevance and scope, Definition of J-integral, Path independence, stress strain relation, Strain Energy Release Rate Vs J-integral

4. **Total Hrs**

Eigen Value Problems: Properties of Eigen values and Eigen Vectors, Torsional, Longitudinal vibration, lateral vibration, Sturm sequence. Subspace iteration and Lanczo's method, Component mode synthesis, Eigen value problems applied to stepped beams and bars

Total Hrs

Dynamic Analysis: Direct integration method. Central difference method. Wilson
method. Newmark method. Mode superposition, Single degree of freedom system response, Multi degree of freedom system response, Rayleigh damping, Condition for stability.

(Note: The related algorithms and codes to be practiced by students)

Total hours to be taught 45

Text book (s)

- John, V. Harvey, Pressure Vessel Design: Nuclear and Chemical Applications, Affiliated East West Press Pvt. Ltd., 1969
- 2. Prasanth Kumar, Elements of Fracture Mechanics, Wheeler Publishing, New Delhi-1999

- 1. Rammurti, Computer Aided Mechanical Design and Analysis, Tata Mc Graw Hill-1992
- 2. Bathe, J., Finite Element Procedures, Prentice Hall of India-1996.

BIT	Autonomous Regulation		Sem	ester-1		AY - 2006-17			
Department		Progra	amme C	ode & Na	ıme	M.E. CA	AD/CAM &	Thermal	
	Mechanical Engineering					Enginee	ering		
Course Code	Course Name	Hours	/ Week		Credit	Maximu	m Marks		
16MEC 105	FINITE ELEMENT	L	Т	Р	С	E	1	Total	
	TECHNIQUES	3	1	0	4	70	30	100	
Objective (s)	Identify mathematical mo Enable the students to fo Enable the students to pe software	rmulate	the des	ign probl	ems into I	FEA .		nalysis	
Outcome (s)	Students are able to 1. implement finite element with hand calculations not and stresses 2. formulate numerically the and stresses 3. formulate numerically the elements then solve for apply FE formulations to heat flux in slabs, walls a sply FE formulations to values and eigen vectors 6. apply FE formulations to	umerica e truss, e plane deflection heat traind plate o dynan s in bars	ally beam and axis ons, stra ansfer of tes nic analy s and be	nd frame symmetric ins and s 1D and s sis of 1D ams	elements c triangula tresses in 2D eleme and 2D e	and solve ar elemen structura nts and so elements a	e for deflects and qualification mechanical	ection, strains adrilateral cs problems mperature and	

1. FIELD PROBLMES AND MODELING

Total Hrs

9

Introduction to Finite Element Method of solving field problems. Stress and Equilibrium. Boundary conditions. Strain-Displacement relations. Stress-strain relations.

One Dimensional Problem: Finite element modeling. Local, natural and global coordinates and shape functions. Potential Energy approach: Assembly of Global stiffness matrix and load vector. Finite element equations, treatment of boundary conditions. Quadratic shape functions

2. ANALYSIS OF TRUSSES AND FRAMES

Total Hrs

9

Analysis of plane truss with number of unknowns not exceeding two at each node.

Analysis of Beams: Element stiffness matrix for two noded, two degrees of freedom per node for beam element. Analysis of frames with two translations and a rotational degree of freedom at each node

3. TWO DIMENSIONAL STRESS ANALYSIS

Total Hrs

9

Finite element modeling of two dimensional stress analysis problems with constant strain triangles treatment of boundary conditions. Two dimensional four noded isoparametric elements treatment of boundary conditions. Two dimensional four noded isoparametric elements and numerical integration. Finite element modeling of Axisymmentric solids subjected of axisymmentric loading with triangular elements.

Convergence requirements and geometric isotropy

4. HEAT TRANSFER PROBLEMS AND DYNAMIC ANALYSIS

Total Hrs

ç

Steady state heat transfer analysis: One dimensional analysis of a fin and two dimensional, conduction analysis of thin plate, Time dependent field problems: Application to one dimensional heat flow in a rod.

Dynamic analysis: Formulation of finite element modeling of Eigen value problem for a stepped bar and beam. Evaluation of Eigen values and Eigen vectors, Analysis of a uniform shaft subjected to torsion using Finite Element Analysis.

5. THREE DIMENSIONAL PROBLEMS IN SRESS ANALYSIS

Total Hrs

9

Finite element formulation of three dimensional problems in stress analysis,

Bending of elastic plates: Thin and Thick plate formulations, Introduction to non-linear problems and Finite Element analysis software's

Total hours to be taught

Text book (s)

- 1. Tirupathi R Chandrupatla and Ashok.D. Belegundu, Introduction of Finite Element in Engineering. Prentice Hall of India, 2004
- 2. Rao S.S., The Finite Element Methods in Engineering, 2nd Edn Pergamon Press, 2001.
- 3. David.V.Hutton, "Fundamentals of Finite Element Analysis", Tata McGraw Hill,2003

References:

- 1. Robert Cook, "Concepts and applications of finite element analysis", 4e, John Wiley and sons, 2009
- 2. Reddy J.N., An Introduction to Finite Element Methods ,Mc Graw Hill Company, 1984
- 3. K..J Bathe, Finite element procedures, 2nd Edn, Prentice Hall of India, 2007
- 4. Logan, D. L. (2011). First course in finite element method, (5th Ed.). Mason, OH: SouthWestern, Cengage Learning.

Department	Autonomous Regulation								
Dopartinent	Mechanical Engineering	Program		de &	Name	M.E. Therr	nal Engin	eerin	g
		Semest			10 III				
Course Code	Course Name	Hours/ V		_	Credit	Maximum	Marks	—	4-1
40MEC 205	COMPLITATIONAL	L	T	P	C	E 70	1	To	
16MEC 205	COMPUTATIONAL FLUID DYNAMICS	3	1	0	4	70	30	10)()
Objective (s)	1. To understand the basic equ						<u> </u>		
	2. To make the students to lear								
	3. To study various types of gri					erical solutio	n.		
	4. To learn the Crank-Nihcolson 5. To prepare the students with					mothode			
	6. To enkindle the students imp			beidei	and ADI	memous			
Outcome (s)	Students will be able to								
	 derive CFD governing equation apply elliptical, parabolic and 					bookword s	nd conto	· diffo	ronoo
	methods .	пурегоог	IC PDE	s anu	ioiwaiu,	Dackwaru a	ina cente	uiiie	rence
	3. understand errors, stability,	consisten	cy and	devel	lop O,H a	nd C grid g	enerated	mode	els.
	4. evaluate the use of Crank-N	lihcolson,	Implicit	and	Explicit n	nethods.			
	5. analyze problem by Jacobi, (
4 DACIC E	6. solve conduction and convect QUATIONS IN FLUID DYNAMICS		ems us	ing F	VM		Total	lua	
							Total I		9
	entum and Energy equations, Na							– N b	·S
equations. Introd	duction to turbulence, Turbulence	models-m	iixing le	ength	model, K	-ε turbulenc	e Model.		
	ICATION OF PDEs						Total H	rs	9
	c and hyperbolic equations, Initial								
Concepts of Fin	ite difference methods – forward,	backward	and ce	ntral	difference	9.			
3 GRID GE	NEDATION								
S SIMP OF	NERATION						Total F	rs	9
Grid Generation	- Types of grid O,H,C. Coordinate				uctured g	ırid generati			9
Grid Generation	-				uctured g	ırid generati			9
Grid Generation Consistency, Sta	- Types of grid O,H,C. Coordinate ability analysis by von Neumann.				uctured o	ırid generati	on, Errors	5,	
Grid Generation Consistency, Sta	- Types of grid O,H,C. Coordinate ability analysis by von Neumann.	Converge	nce crit	eria.			on, Errors	irs	9
Grid Generation Consistency, Sta 4 FINITE D Finite difference	- Types of grid O,H,C. Coordinate ability analysis by von Neumann. IFFERENCE SOLUTIONS a solutions-Parabolic PDEs – Eul	Converge ler, Crank	nce crit	eria. Ison,	Implicit r	nethods, Ell	on, Errors Total Fiptic PDE	s, rs	9 Jacobi,
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Grid Generation Consistency, Sta 4 FINITE D Finite difference Gauss Seidel, method & MAC	- Types of grid O,H,C. Coordinate ability analysis by von Neumann. (IFFERENCE SOLUTIONS e solutions-Parabolic PDEs – Eul ADI, methods. FD- solution for Method	Converge ler, Crank	nce crit	eria. Ison,	Implicit r	nethods, Ell	Total Fiptic PDE	s, rs s - v	9 Jacobi,
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BIT	Autonomous Regulation		Sem	ester-1			AY - 2006	5-17	
Department	Mechanical Engineering	Progra	amme C	ode & Na	ame	M.E. CA	ND/CAM		
Course		Hours	/ Week		Credit	Maximu	m Marks		
Code	Course Name								
16MEE101	FAILURE ANALYSIS AND	L	Т	Р	С	Е	1	Total	
	DESIGN	3	1	0	4	70	30	100	
Objective (s)		 To understand importance of design and its morphology To understand buckling phenomenon due to combined external pressure and axial loading 							
Outcome (s)	1. design methodology and 2. different creative and inv 3. different types of design 4. concept of buckling of cy 5. the fundamentals of frac prediction and various st 6. basic crack propagation fracture toughness of we	I variou ventive proces vlinders ture, fra tress th conce	problemes, concest under was acture ty eories of the probleme.	solving tepts of releasions lost arious lost pes and failure v	echniques iable and ading con concepts essels	s safe desi ditions of fatigue	gn crack grov		

1. Total Hrs

Importance of design- The design process-Considerations of Good Design – Morphology of Design – Organization for design– Computer Aided Engineering – Concurrent Engineering – Product and process cycles – Market Identification – Competition Bench marking. Identification of customer needs- customer requirements- Product Design Specifications- Human Factors in Design – Ergonomics and Aesthetics

2. Total Hrs 10

Creativity and Problem Solving – Creativity methods-Theory of Inventive Problem Solving (TRIZ) – Conceptual decomposition-Generating design concepts-Axiomatic Design – Evaluation methods-Embodiment Design-Product Architecture-Configuration Design-Parametric Design. Role of models in design-Mathematical Modeling – Simulation – Design for Reliability – Introduction to Robust Design-Failure mode Effect Analysis

3. Buckling phenomenon – Elastic Buckling of circular ring and cylinders under external pressure – collapse of thick walled cylinders or tubes under external pressure – Effect of supports on Elastic Buckling of Cylinders – Buckling

under combined External pressure and axial loading

4. Total Hrs 10

Failure analysis and determination of stress patterns from plastic Flow observations – Dynamic loading– Fracture types in tension—Fatigue crack growth– Fatigue life prediction- Cumulative fatigue damage-Stress theory of failure vessels-Thermal stress fatigue

5. Total Hrs 10

Introduction –Through cracks emanating from holes – Corner cracks at holes – Cracks approaching holes-Combined loading-Fatigue crack growth binder- Mixed mode loading-Fracture toughness of weld metals-Service failure analysis

Total hours to be taught

Text book (s)

- 1. Dieter, George E., —Engineering Design A Materials and Processing Approachll, McGraw Hill, International Editions, Singapore, 2000.
- 2. Pahl, G, and Beitz, W., II Engineering Design II, Springer Verlag, NY. 1984

- 1. David Broek, IElementary Engineering Fracture Mechanics —, Fifthoff and Noerdhoff International Publisher, 1978
- 2. Preshant Kumar, —Elements of Fracture MechanicsII, Wheeler Publishing, 1999
- 3. John F. Harvey, Theory and Design of Pressure Vessels, CBS Publishers and Distributors, 1987
- 4. Henry H. Bedner, —Pressure Vessels, Design Hand Book, CBS publishers and Distributors, , 1987

CBIT	Autonomous Regulation	Semester-1					AY - 2006-17						
Department	Mechanical Engineering	Progr	amme C	ode & Na	ıme	M.E. CA	AD/CAM						
Course Code	Course Name	Hours	/ Week		Credit	Maximu	m Marks						
16MEE 102	INTEGRATED	L	Т	Р	С	Е	I	То	tal				
	MECHANICAL DESIGN	3	0	0	3	70							
Objective (s)	To know the importance of I components To learn design criteria of magnetic and the second of the second	achine iples to epts of therma	compor design machine	ents acco different of tools, au	ording to s gears and tomobiles	standards gear box and med	nachine and mechanical dards and Theories of failure ar boxes. d mechanical handling						
Outcome (s)	1. Be able to know the importal and manufacturing 2. Be able to do the complete design and machining allowan 3. Be able to do the design and 4. Be able to do the design of equipments for dynamics and 5. Be able to design of Mechan	design ces aco d analy brakes therma	and ana cording t sis of Di of mach I aspects	lysis of shoot standar fferent ge ine tools, s.	nafts, bea ds and re ars and g automob	rings and quiremen ear boxes	casings b ats. s.	y consic	lering				
Phases of de	sign – Standardization and ir	ntercha	ngeabilit	y of mad	chine ele	ments -			nction				

Phases of design – Standardization and interchangeability of machine elements - Process and Function Tolerances – Individual and group tolerances – Selection of fits for different design situations – Design for assembly and modular constructions – Concepts of integration –BIS, ISO, DIN, BS, ASTM Standards.

Oblique stresses – Transformation Matrix – Principal stresses – Maximum shear stress - Theories of Failure

- Ductile vs. brittle component design -

Analysis and Design of shafts for different applications – integrated design of shaft, bearing and casing – Design for rigidity.

2. Total Hrs 9

Principles of gear tooth action – Gear correction – Gear tooth failure modes – Stresses and loads – Component design of spur, helical, bevel and worm gears – Design for sub assembly – Integrated design of

speed reducers and multi-speed gear boxes – application of software packages

7 Total Hrs

Dynamics and thermal aspects of vehicle braking – Integrated design of brakes for machine tools, automobiles and mechanical handling equipments

4. Total Hrs 9

Integrated Design of systems consisting of shaft, bearings, springs, motor, gears, belt, rope, chain, pulleys, Cam & Follower, flywheel etc. Example - Design of Elevators, Escalators, Gear Box, Valve gear Mechanisms, Machine Tools

Total hours to be taught

Text book (s)

- 1. L. R., —Machine Design An Integrated Approach Pearson Education, 2005
- 2. Newcomb, T.P. and Spur, R.T., —Automobile Brakes and Braking SystemsII, Chapman and Hall, 2nd Edition,1975.
- 3. Maitra G.M., —Hand Book of Gear DesignII, Tata McGraw Hill, 1985
- 4. Shigley, J.E., —Mechanical Engineering DesignII, McGraw Hill, 1986
- 5. Prasad. L. V., —Machine Designll, Tata McGraw Hill, New Delhi, 1992
- 6. Alexandrov, M., Materials Handling Equipments, MIR Publishers, 1981
- 7. Boltzharol, A., Materials Handling Handbook, The Ronald Press Company, 1958

Approved Data Books:

- 1. .S.G. Tech., —Design Data Bookl, Kalaikathir Achchagam, Coimbatore, 2003.
- 2. Lingaiah. K. and Narayana Iyengar, —Machine Design Data Hand Bookll, Vol. 1 & 2, Suma 1983

CBIT	Autonomous Regulation	Semester-1 AY - 2006-17							
Department	Mechanical Engineering	Progr	amme C	ode & Na	ame		M.E. CAD	D/CAM	
Course Code	Course Name	Hours	s/ Week		Credit	Maximu	m Marks		
16MEE 102		L	Т	Р	С	Е	I	To	otal
	ROBOTIC ENGINEERING	3	0	0	3	70	30	10	00
Objective (s)	☐ To be familiar with the brief								
	☐ To give the student familiari								
	☐ To give knowledge about ro				_				
	☐ To give knowledge about va								
Outcome (s)	Students will be equipped w								atios.
	2. Students will have good kno			obot end	effectors	and their	design co	ncepts.	
	Understand different orientations of robot								
	4. Students will be familiarized					ot and			
	5. Able to solve the static and								
6. Students will be equipped with the principles of various Sensors, their applications in robots and									
concept of robot vision 1. Total Hrs 9									
	unes of release Overview of rele	ماريم م				alailite ana			_
	ypes of robots, Overview of robots, Robot configurations and co								
	ypes of grippers, vacuum and								
	cations of robots, specifications					diffatio, i	iyaraano c	aria cic	Julioui
2.	· 1						Total	Hrs	9
Rotation matric	ces, Euler angle and RPY re	epreser	ntation,	Homogei	neous tra	nsformati	on matric	es, De	navit-
Hartenberg not	tation, representation of absolu	ite pos	ition an	d orienta	ition in te	erms of jo	oint paran	neters,	direct
kinematics.									
3.							Total		9
	atics, inverse orientation, inve								
	ask space interpolation, execution					ased mo	tion plann	ing: The	e Bug
	Tangent Bug Algorithm, The Inc	rement	al Voron	oi Graph.	•				
4.							Total		9
	llysis of RP type and RR type pla							Newton	-
	ons of RR and RP type planar ro								
feedback, actuator models, nonlinearity of manipulator models, force feedback, hybrid control Total Hrs 9									
	Sensors and controllers: Internal and external sensors, position, velocity and acceleration sensors, proximity								
sensors, force sensors, laser range finder									
	nage processing fundamentals for	ar robot	ic annlic	ations in	ann acui	icition an	d proproce	ecina	
	and region characterization object								
Cogmontation a	and region enalacterization object	r recog	i iitioi i by		tal hours			-	
Toyt book (a)				10	tar riouro	io bo laag	j		<u> </u>

Text book (s)

- 1. Nagrath and Mittal, —Robotics and Controll, Tata McGraw-Hill, 2003
- 2. Spong and Vidhyasagar, —Robot Dynamics and Controlll, John Wiley and sons, 2008

References:

- 1. Fu. K.S, Gonzalez, R.C., Lee, C.S.G, Robotics, control, sensing, Vision and Intelligence, McGraw Hill International, 1987
- Steve LaValle, —Planning AlgorithmsII, Cambridge Univ. Press, New York, 2006
 Howie Choset, Kevin Lynch, Seth Hutchinson, George Kantor, Wolfram Burgard, Lydia Kavraki and Sebastian Thurn, —Principles of Robot Motion: Theory, Algorithms, and Implementations , Prentice Hall of India, 2005

CBIT	Autonomous Regulation		Sem	ester-1	AY - 2006	-17						
Department	Mechanical Engineering	Programme Code & Name					M.E. CAD/CAM					
Course Code	Course Name	Hours	/ Week		Credit	Maximu	Maximum Marks					
16MEE 103	PROGRAMMING	L	Т	Р	С	E	I	To	tal			
	METHODOLOGY AND DATA STRUCTURES	3	0	30	10	00						
Objective (s)	 To encourage the stud 	 To improve logical thinking of the students. To encourage the student to use their own code to solve mechanical engineering Problems. 										
Outcome (s)	1. Different types of data storage and their structures 2. Implementing the concepts with programming in 'C' 3. Apply different sorting techniques in Mechanical engineering Applications 4. Classify the different Data Structures 5. differentiate between Linked lists, stacks and queues 6. Understand the concept of Trees and their traversals											
1.	•						Total	Hrs	9			
	Methodology: Introduction, Algroject Development.	jorithm,	, Data F	low Diag	rams, De	cision Tre	e, Decisio	n Table	e and			
2. Total Hrs 9												
Programming in 'C' : Data types & Memory size, Expressions, Statements, Operators, Control flows, Arrays, Pointers, Structures, Functions, Dynamic Memory Allocation and Simple programs in Mechanical Engineering.												
3.	Total Hrs 9											

Sorting and Searching Techniques: Selection sort, Quick sort, Radix sort, Heap sort. Linear search, Binary search trees and Applications in Mechanical Engineering

4. Total Hrs 9

Data Structures: Classification of Data Structures, Definitions of Linked Lists, Double Linked Lists, Stacks and Queues. Operations and Implementations of Stack, Queues and Linked List. General and Mechanical Engineering Applications

5. Total Hrs 9
Advanced Data Structures: Tree, Basic Terminology, Binary Trees, Operations on Binary tree, Tree traversals,

Graph, Graph representation Adjacency matrix, Adjacency Lists and Applications

Total hours to be taught

Text book (s)

- G.Michael Schneider, Steven C.Bruell, —Concepts in Data Structures and Software Development", Jaico Publishing House, 2002
- 2. Kernighan B.W, Ritchie D.M, —The C Programming Language", 2nd Edition, Prentice-Hall of India, 2003

References:

- 1. Kruse RL, Bruce RL, Cloris Lt, —Data Structures and Program Design in C". PHI, 1991
- 2. Hyer, M.W., Stress Analysis of Fibre Reinforced Composite Materials, Mc Graw Hill Co., 1998.
- 3. Trembly and Sorenson, —An Introduction to Data Structures with application", McGraw Hill, 1984

CBIT	Autonomous Regulation	Semester-1					AY - 200	AY - 2006-17		
Department	Mechanical Engineering	Programme Code & Name M.E. There					nermal Eng	gineering	g	
Course Code	Course Name	Hours	/ Week		Credit	Maximu	ım Marks			
16MEE 104	OPTIMIZATION	L	Т	Р	С	Е	1	To	tal	
	TECHNIQUES	3	1	0	4	70	30	10	00	
Objective (s)	1. To Understand the need of	the opt	imizatior	method	S.	l				
(-)	2. To introduce the fundament					iques				
	3. To provide students with the						d formula	te optim	ization	
	problems		Ū		•			•		
	4. To make the learners aware									
	5. To provide the concepts of					methods	of for co	nstraine	ed and	
	unconstrained problems in									
	6. Get a broad picture of the v				timization	methods	used in er	ngineeri	ng.	
Outcome (s)	Formulate and solve Linear									
	2. Apply different techniques to				amming p	roblem				
	3. Implement constrained optim									
	4. Analyze dynamic programm									
	5. Develop schedule for project			R I/CPIV	i technique	es				
4 111500 00	6. Apply Queuing theory to real life situations 1. LINEAR AND TRASPORTATION PROBLEMS Total Hrs 9									
	ptimization Problem, Linear Pro		ning: Cin	anlay Ma	thod Dov	iood Sim			9	
	pumization Problem, Linear Problem, Linear Problem, End Transpo				etnou, Rev	isea Sin	ipiex ivieti	ioa, Sei	risitivity	
2. NON-LINEAR		Jitalion	riobien				Total	Urc	9	
	gramming: Approach, Converge	nce and	l Scaling	of Design	ın vəriəhlə	e: Hncon		1113	9	
	Pirect Search Methods: Random									
	pest Descent, Conjugate Gradie						ot Ocaron			
	R PROGRAMMING	,	,	<u> </u>			Total	Hrs	9	
	timization Direct Methods: Lag	range l	Multiplie	rs, Kuhn-	Tucker, c	onditions	. Beal's m	ethod, I	ndirect	
	Function and Applications	3.		-, -	, ,		,	,		
4. DYNAMIC PI	ROGRAMMING						Total	Hrs	9	
	Dynamic Programming; Concept									
	s Dynamic Programming with A									
	Branch and Bound method; Int	roduction	on to Ge	netic Algo	orithms, pa	rticle sw			1	
5. PROJECT SCHEDULING Total Hrs 9										
	d Scheduling, Project Schedul									
scheduling; Queuing Theory, Single and multi server models; Queues with combined arrivals and departures;										
				o, wacac			arrivale al	ia acpe	artaroo,	
	orities for service									
Queues with pri					tal hours t			ıl Hrs	45	
Queues with pri	orities for service			То	tal hours t	o be tauç	ght Tot a			
Queues with pri Text book (s) 1. Rao,S.S. Eng		and Pra	ctice", N	To ew Age Ir	tal hours t	o be tauç	ght Tot a			

- Haug, E. J. and Arora, J.S., Applied Optimal Design, Wiley Intel Science Publication, NT, Reference(s)
 Douglas J. Willde, "Globally Optimal Design", Jhon Wiley & Sons, New York, 1978
 Johnson Ray C., "Optimum Design of Mechanical Elements", John Wiley & Sons, 1981.
 S.D. Sharma, S.D. "Operations Research", Khanna Publications, 2001.
 David Goldberg, "Genetic Algorithms", pearson publications, 2006.
 Maurice cleric, "Particle Swarm Optimization", ISTE Publications, 2006
 Prem Kumar Gupta, "Operations Research", S Chand publications, 2008

CBIT	Autonomous Regulation		Sen	nester-1		AY - 2006-17					
Department	Mechanical Engineering	Progr	amme C	ode & Na	ame		M.E. CAD	D/CAM			
Course Code	Course Name	Hours	/ Week		Credit	Maximu	ım Marks				
16MEE105	VIBRATION ANALYSIS	L	Т	Р	С	Е	_	То	tal		
	AND CONDITION MONITORING	3	0	0	3	70	30	10	00		
Objective (s)	 To familiarization with 	the bas	sics of vi	bration m	easureme	ents					
	 To apply the vibration 	princip	les for c	ondition i	monitoring	of machi	inery				
Outcome (s)	1. Understand the Causes of \										
	2. Understand Single degree a										
	transient characteristics of vibi		simple h	armonic r	notion, pe	riodic mo	tion, peak	to			
	Peak,RMS and average values. 3. Vibration measuring instruments, display and recording to elements, frequency analysis										
				na recora	ing to eler	nents, fre	quency ar	naiysis			
	and filters, Vibration limits and 4. Know and be able to explain			o bacies	of CM:						
						al CM:					
	5. Be aware of some methods and procedures applied for general CM;6. Appreciate and understand the basic idea behind vibration-based structural health										
	monitoring and vibration- base										
1.	<u>,</u>						Total		9		
Causes and effe	ects of vibration. Vibrations of Si	ngle De	egree, T	wo Degre	e and Mul	ti Degree	of freedo	m			
	y state and transient characteris										
2.							Total	Hrs	9		
	Condition Monitoring, Failure typ										
	of vibration – SHM, Periodic mo		splacem	ent, Velo	city and a	cceleratio	n Peak to	peak &			
	d logarithmic scales and phase a	angle					Tatal	Llua	_		
3.	ouring instruments vibration to	opodus	oro oio	nal aana	litioning	lomonto	Total		9		
	suring instruments, vibration tration tration meters and analyzers	ansuuc	ers, sig	nai conc	allioning e	iements.	Display	and rec	cording		
4.	nion meters and analyzers)			Total	Hre	9		
	toring through vibration analysis.	Freque	ency ana	lveie Filt	ers Vibrat	tion signa			3		
	ion limits and standards. Contam										
techniques	and diameter contain		, 0.0,	_ _ u							
5.							Total	Hrs	9		
	n measuring techniques - Chan-										
measurement, I	Kurtosis, Acoustic emission mor	nitoring	, Cepstr	um analy	sis, Modal	l analysis	, critical s	peed ar	nalysis,		
Shaft –orbit & p	osition analysis								1		
				To	tal hours t	o be taug	ht Tota	al Hrs	45		

Text book (s)

- 1. Collacott, R.A., Mechanical Fault Diagnosis and Condition Monitoring, Chapman & Hall, London, 1982
- 2. John S. Mitchell, Introduction to Machinery Analysis and Monitoring, Penn Well Books, Penn Well Publishing Company, Tulsa, Oklahoma, 1993.

- 1. Nakra, B.C. Yadava, G.S. and Thuested, L., Vibration Measurement and Analysis, National Productivity Council, New Delhi, 1989
 2. Pox and Zenkins, Time Series Analysis
- 3. A.H. Search, Vibration and Time Series Analysis

CBIT	Autonomous Regulation										
			ogramn	ne Co	de &		D/CAM &	Therm	al		
Department	Mechanical Engineering		Nam	ne		Engineer	ring				
Course Code	Course Name	nester-l	/ Week		Credit	Movimu	m Marks				
Course Code	Course Name	L	T	Р	Credit	F	in Marks	Т	otal		
	ENGINEERING RESEARCH					 		<u>'</u>			
16MEE 107	METHODOLOGY	3	0	0	3	70	30		100		
Objective (s)	To motivate the students to choose										
	2. To make the students to formulate t					20					
	3. To identify various sources for litera4. To prepare the research design	lure rev	new and	u dala	Collection	on.					
	5. To equip the students with good me	thods t	o analv	ze the	collecte	ed data					
	6. To write a report and interpret the re		,								
Outcome (s)	Students will be able to										
	1. define research problem										
	2. review and asses the quality of liter				ources.						
	3. understand and develop various research designs.4. collect the data by various methods: observation, interview, questionnaires.										
	5. analyze problem by statistical techniques: ANOVA, F-test, Chi-square										
	6. improve the style and format of writi						al report				
1 Res	search Methodology:						Total H	'S	9		
	ethodology: Objectives and Motivation										
	of Research, Research Methods verses I						eria of Go	od Re	search,		
	countered by Researchers in India, Bene Research Problem: Selection of Research						o Droblo	m Too	shniquo		
	efining a Problem	al CH F IC	Joiem, i	NECES	SSILY OF L	reming u	ie riobie	III, 1 6 0	Jiiiique		
							-				
	terature Survey: urvey: Importance and purpose of Lite	roturo	Curvo			floforme	Total F		9		
	urvey. Importance and purpose of Lite urnals and Articles, Information through Ir			, 30	ources o	i illioillia	alion, Ass	essine	ant or		
	eview: Need of Review, Guidelines for R			of Re	esearch	Review					
	esearch Design:						Total	Hrs	9		
Research D	esign: Meaning of Research Design,	Need	of Rese	earch	Design	, Feature	of a G	ood D	esign,		
	ncepts Related to Research Design, Dif						ciples of I	Experir	nental		
	eloping a Research Plan, Steps in sample	e desigi	າ, types	of sa	ımple de	signs.					
4 Data Collection: Total Hrs 9											
Data Collect	ion: Methods of data collection, import	ance o	t Paran	netric	test, te	sting of p	proportion	s, test	ing of		
Data Analys	vo normal population, and Non Parametr s: Tests for significance: Chi-square, AN	OVA F	relation -test	เบยเพ	reen Spe	annan S	is and Ke	enuairs	5 VV		
	terpretation and report writing:	<i>∨ ∨ ∧</i> , 1	1001.				Total H	rs.	9		
	Interpretation and report writing: 10tal Hrs 9 Interpretation and report writing: Meaning of interpretation, layout of research report, Types of reports,										

Proposal Text Book (s):

Mechanics of writing a report.

1. C.R Kothari, Research Methodology, Methods & Technique; New Age International Publishers, 2004

Research Proposal Preparation: Writing a Research Proposal and Research Report, Writing Research Grant

2. R. Ganesan, Research Methodology for Engineers, MJP Publishers, 2011

References:

- 3. Y.P. Agarwal, Statistical Methods: Concepts, Application and Computation, Sterling Publs., Pvt., Ltd., New Delhi, 2004
- 4. Vijay Upagade and Aravind Shende, Research Methodology, S. Chand & Company Ltd., New Delhi, 2009
- 5. P. Ramdass and A. Wilson Aruni, Research and Writing across the Disciplines, MJP Publishers

CBIT	Autonomous Regulation		Ser	nester-1		AY - 2006-17				
Department	Mechanical Engineering	Programme Code & Name					M.E. CAD	D/CAM		
Course Code	Course Name	Hours	/ Week		Credit	Maximu	Maximum Marks			
16MEE 108		L	Т	Р	С	Е	I	To	tal	
	TRIBOLOGY IN DESIGN	3	0	0	3	70	30	10	00	
Objective (s)		in the friction, wear and lubrication aspects of machine components naterial properties which influence the tribological characteristics of								
Outcome (s)	After the completion of the count of the cou	surface and wo nts and tact an materia	topogra ear asp d lubrica d rough al / su	ophy and opects of reation regination regination surface curface properties.	can model machine imes for c contact properties	lifferent based	operating	conditi tribol		
1	1						Total	Urc	0	

Total Hrs

Topography of Surfaces - Surface features -Properties and measurement - Surface interaction - Adhesive Theory of Sliding Friction -Rolling Friction-Friction properties of metallic and non-metallic materials - friction in extreme conditions -Thermal considerations in sliding contact

2. **Total Hrs** 9

Types of wear – Mechanism of various types of wear – Laws of wear –Theoretical wear models-Wear of Metals and Non metals - Surface treatments - Surface modifications - surface coatings methods- Surface Topography

measurements -Laser methods - instrumentation - International standards in friction and wear measurements. 3. **Total Hrs**

Lubricants and their physical properties- Viscosity and other properties of oils -Additives-and selection of Lubricants- Lubricants standards ISO, SAE, AGMA, BIS standards - Lubrication Regimes - Solid Lubrication-Dry and marginally lubricated contacts- Boundary Lubrication- Hydrodynamic lubrication — Elasto and plasto hydrodynamic - Magneto hydrodynamic lubrication - Hydro static lubrication - Gas lubrication

Total Hrs

Reynolds Equation,-Assumptions and limitations-One and two dimensional Reynolds Equation-Reynolds and Sommerfeld boundary conditions- Pressure wave, flow, load capacity and friction calculations in Hydrodynamic bearings-Long and short bearings-Pad bearings and Journal bearings- Squeeze film effects-Thermal considerations-Hydrostatic lubrication of Pad bearing-Pressure, flow, load and friction calculations-Stiffness considerations- Various types of flow restrictors in hydrostatic bearings

Total Hrs

Rolling contacts of Elastic solids- contact stresses - Hertzian stress equation- Spherical and cylindrical contacts-Contact Fatigue life- Oil film effects- Elasto Hydrodynamic lubrication Theory-Soft and hard EHL-Reynolds equation for elasto hydrodynamic lubrication - Film shape within and outside contact zones-Film thickness and friction calculation- Rolling bearings- Stresses and deflections-Traction drives

Total hours to be taught Total Hrs Text book (s)

- 1. Rabinowicz.E, —Friction and Wear of materials II, John Willey & Sons , UK, 1995
- Cameron, A. —Basic Lubrication Theoryll, Ellis Herward Ltd., UK, 1981
- 3. Halling, J. (Editor) —Principles of Tribology —, Macmillian 1984
- 4. Williams J.A. Engineering Tribologyll, Oxford Univ. Press, 1994
- 5. .K.Basu, S.N.Sengupta & B.B.Ahuja , ||Fundamentals of Tribology||, Prentice Hall of India Pvt. Ltd., New Delhi, 2005
 - 6. G.W.Stachowiak & A.W .Batchelor, Engineering Tribology, Butterworth-Heinemann, UK, 2005

CBIT	Autonomous Regulation		Sen	nester-1		AY - 2006-17			
Department	Mechanical Engineering	Progra	amme C	ode & Na	ame		M.E. CAD)/CAM	
Course Code	Course Name	Hours	/ Week		Credit	Maximum Marks			
16MEE 109	ADVANCED	L	Т	Р	С	Е	- 1	To	tal
	MECHANICS OF MATERIALS	3	0	0	3	70	30	10	00
Objective (s)	 To understand the var 	ious str	esses a	nd deflec	tions in be	ams			
	To understand the street	ess-stra	in relation	ons and f	ailure thec	ries			
Outcome (s)	Students will be able to 1. understand the analys 2. analyze and design th 3. determine the stresses 4. locate the shear centre 5. Determine the stresses 6. calculate the residual noncircular cross-sect	e colums due to e of thir es in cu stresse	nns o asymm n-walled rved bea	etric ben sections ams	ding				sion of
1.	Total Hrs 9								

Stress-Strain relations and general equations of elasticity in Cartesian, Polar and curvilinear coordinates, differential equations of equilibrium-compatibility-boundary conditions-representation of three-dimensional stress

differential equations of equilibrium-compatibility-boundary conditions-representation of three-dimensional stress of a tension generalized hook's law - St. Venant's principle - plane stress - Airy's stress function. Energy methods

2. Location of shear center for various thin sections - shear flows. Stresses and Deflections in beams subjected to unsymmetrical loading-kern of a section

3. Total Hrs 9
Circumference and radial stresses – deflections - curved beam with restrained ends - closed ring subjected to

concentrated load and uniform load - chain links and crane hooks. Solution of rectangular

4. Total Hrs

Torsion of rectangular cross section - St. Venants theory - elastic membrane analogy - Prandtl's stress function - torsional stress in hollow thin walled tub

5. Total Hrs 9
Radial and tangential stresses in solid disc and ring of uniform thickness and varying thickness allowable speeds.

9

Methods of computing contact stress deflection of bodies in point and line contact applications

Total hours to be taught | Total Hrs | 45

Text book (s)

- 1. Arthur P Boresi, Richard J. Schmidt, —Advanced mechanics of materials II, John Wiley, 2002
- 2. Timoshenko and Goodier, "Theory of Elasticity", McGraw Hill
- 3. Robert D. Cook, Warren C. Young, "Advanced Mechanics of Materials", Mc-millan pub. Co., 1985
- 4. Srinath. L.S., —Advanced Mechanics of solidsl, Tata McGraw Hill, 1992
- 5. G H Ryder Strength of Materials Macmillan, India Ltd, 2007
- 6. Allan F. Bower, —Applied Mechanics of SolidsII, CRC press Special Indian Edition -2012, 2010
- 7. K. Baskar and T.K. Varadan, —Theory of Isotropic/Orthotropic Elasticityll, Ane Books Pvt. Ltd., New Delhi, 2009

CBIT	Autonomous Regulation		Sen	nester-1			AY - 200	06-17		
Department	Mechanical Engineering			ode & Na	ame		M.E. CAD	D/CAM		
Course Code	Course Name	Hours	/ Week		Credit	Maximu	ım Marks			
16MEE 110	MECHANICS OF	L	Т	Р	С	Ε	I	То	tal	
	COMPOSITE MATERIALS	3	0	0	3	70	30	10	00	
Objective (s) Outcome (s)	1. An ability to identify composites, as well as 2. An ability to predict the properties. 3. An ability to analyze from lamina properties 4. An ability to predict the 1. Classify the composite 2. Recognize the fundament	s some he elas a lamii s. e failure es, type nentals	common stic prop nated pla e strengt s of rein of orthol	n manufarerties of ate in beath of a lamertropic marerties of the manufacture of the manu	cturing tectifiber community incommunity i	chniques. posites b luding fin mposite p es and ph	als used pased on the ding laminolate pases.	in comments in com	mercial stituent perties	
	 Understand different fabrication methods of composites. Demonstrate the fundamentals of directional stresses and strains. Transformation of stress and strain. Understand the failure of composites including fracture. Analyze different types of composite structures using plate and shell theory 									
1.							Total		9	
	bres, Matrix materials, interfact tes and carbon carbon composit		mer ma	atrix com	posites, n	netal mat	rix compo	osites, c	eramic	
2.	les and carbon carbon composit	.63.					Total	Hrs	9	
Micromechanics approach, Halpi matrix to fibre	s of lamina and mechanical propin- in-Tsai equations. Thermal prop						omechanic transfer fro	cal om		
3.							Total		9	
stiffness and o	ics of lamina: Elastic constants compliances. Variation of laminations with orientation, inter-laminated beams	na prop	erties v	vith orien	ntation, ar	nalysis of	laminate	d comp	osites,	
4.							Total	Hrs	9	
fracture modes failure, fatigue o	re, fatigue and design: Tensile a in composites: single and multip of laminate composites. Effect of ory, max strain criteria, maximum	ole fract f variabi	ures, de lity of fib	-bonding, ore streng	, fibre pullo th. Streng	out and d th of an c	e-lamination orthotropic	on Iamina:		

Max stress theory, max strain criteria, maximum work (Tsai-Hill) criterion, quadratic interaction criteria.

Designing with composite materials

5.

Analysis of laminated plates and shells: Plate equilibrium equations, Bending of composite plates, Levy and Navier

solution for plates of composite materials. Analysis of composite cylindrical shells under axially symmetric loads.

Total hours to be taught | Total Hrs | 45

Text book (s)

- 1. Jones, R.M., Mechanics of Composite Materials, Mc Graw Hill Co., 1967
- 2. B.D.Agarwal et.al, *Analysis and performance of fiber composites*,3rd edition, Wiley sons., 2013
- 3. Ever J Barbero, Introduction to composite materials design, Taylor &Francis, 1999.

- 1. Whitney, I.M. Daniel, R.B. Pipes, Experimental Mechanics of Fibre Reinforced Composite Materials, Prentice Hall, 1984
- 2. Hyer, M.W., Stress Analysis of Fibre Reinforced Composite Materials, Mc Graw Hill Co., 1998
- 3. Carl. T. Herakovich, Mechanics of Fibrous Composites, John Wiley Sons Inc., 1998.

CBIT	Autonomous Regulation		Sen	nester-1			AY - 200	6-17				
Department	Mechanical Engineering	Progr	amme C	ode & Na	ame		M.E. CAD)/CAM				
Course Code	Course Name	Hours	/ Week		Credit	Maximu	Maximum Marks					
16MEE 111	THEORY OF ELASTICITY	L	Т	Р	С	E	1	To	tal			
	AND PLASTICITY	3	0	0	3	70	30	10	00			
Objective (s)		 solve the problems selected to stress-strain tensors and an constitutive relations apply suitable plasticity relations to solve the problems in various metal forming operations 										
Outcome (s)	1. demonstrate the unde 2. understanding of conc 3. solve the problems rel 4. to apply the constitut problem solving 5. apply plasticity relation 6. can choose and apply	epts of ated to ive equ	strain stress 8 lations, o	strain a compatib	nd also the ility equati	eir relatio	ns in isotro	•				
1		•					Total	Hre	a			

1. | Total Hrs | 9 | Basic Concepts of Stress: Definition, State of Stress at a point, Stress tensor, invariants of stress tensor, principle stresses, stress ellipsoid, derivation for maximum shear stress and planes of maximum shear stress, octahedral shear stress, Deviatoric and Hydrostatic components of stress, Invariance of Deviatoric stress tensor, plane stress

2. Total Hrs 9

Basic concepts of Strain: Deformation tensor, Strain tensor and rotation tensor; invariants of strain tensor, principle strains, derivation for maximum shear strain and planes of maximum shear strain, octahedral shear strain, Deviatoric and Hydrostatic components of strain tensor, Invariance of Deviatoric strain tensor, plane strain.

3. Total Hrs 9

Generalized Hooke's Law: Stress-strain relationships for an isotropic body for three dimensional stress space, for plane stress and plane strain conditions, differential equations of equilibrium, compatibility equations, Material (D) matrix for Orthotropic Materials

4. | Total Hrs | 9

True stress and true strain, von-Mise's and Tresca yield criteria, Haigh–Westergard stress space representation of von - Mise's and Tresca yield criteria, effective stress and effective strain, St. Venants theory of plastic flow, Prandtle–Reuss and Levy–Mise's constitutive equations of plastic flow, Strain hardening and work hardening theories, work of plastic deformation.

5. Total Hrs 9

Analysis methods: Slab method, Slip line field method, uniform deformation energy method, upper and lower bound solutions. Application of Slab method to forging, wire drawing, extrusion and rolling processes

Total hours to be taught Total Hrs 45

Text book (s)

- 1. Timoshenko and Goodieer, *Theory of Elasticity*, Mcgraw Hill Publications 3rd Edition
- 2. Madleson, Theory of Plasticity

- 1. J. Chakrabarty, Theory of Plasticity, 2" edition, McGraw Hill Publications 1998
- 2. George E Dieter, Mechanical Metallurgy, McGraw Hill Publications 1988

CBIT	Autonomous Regulation		Sen	nester-1			AY - 200	06-17	
Department	Mechanical Engineering	Progr	amme C	ode & Na	ame		M.E. CAI	D/CAM	
Course Code	Course Name	Hours	/ Week		Credit	Maximu	ım Marks		
16MEE 112	EXPERIMENTAL	L	Т	Р	С	Е	I	To	otal
	TECHNIQUES AND DATA	3	0	0	3	70	30	1	00
Objective (s)	ANALYSIS 1. To get acquainted	with in	oproving	quality	of produ	ot/proces	o by oti	Idvina	vorious
Objective (s)	parameters	WILII III	iproving	quality	oi piodu	ci/proces	ss by sit	laying	various
	2. To gain the knowledge	e regard	dina imp	rovement	of produc	tivity			
Outcome (s)	Show the general prin				o produc				
(0)	2. Classify and apply diff				nverting cu	itting forc	es into su	itable si	gnals
	State the design requirements of tool-force dynamometers								
Understand various surface measurement aspects									
5. Able to apply Taguchi methods for different optimization problems									
1.							Tota		9
	of Cutting Forces: Strain g								eristics.
Dynamometer construction, Bridge circuits. Instrumentation and calibration. Displacement and strain									
measurements by photoelasticity. Holography, interferometer, Moir techniques, strain gauge rosettes									
2. Total Hrs 9									
	leasurement: Circuits and instr					ers viz, k	oimetallic,		
	electrical resistance, thermister						: ! . ! ! !	-l -	
	ent: Transducers for flow meas							ds.	
	I drag methods. Vortex shreddin ow visualization techniques, Sha								
3.	ow visualization teeriniques, on	adow g	тарпо, О	ormerer p	onologiapi	ily. Ilitori	Tota	Hrs	9
	tudies: Optical and electron m	icrosco	ny X-R	av diffra	ction Bra	na's Law			
	al structure and residual st								
	Micro hardness, roughness,								
machines			, ,					,	3
4.							Tota	Hrs	9
Experiment de	esign & data analysis: Statist	ical me	ethods,	Randomi	sed block	design,	Latin an	d ortho	gonal
	rial design. Replication and rand					_			_
	Deterministic and random data								
	ression modeling, direct and	dinter	action e	effects. A	ANOVA,	F-test.	Time Ser	ies ana	alysis,
Autocorrelation and autoregressive modeling									
5.							Tota		9
	ds: Experiment design and plant					ear grap	hs. Additiv	e cause	e effect
	ation of response level. Identifica	ation of	LIPSIUN 2		Tactore				
Performance ev	all attack and for that attack to the						! !		_
	raluation and Optimization by sig	gnal to i		ios. Conc				oplicatio	n. 45

Text book (s)

- 1. Holman, J.P.: Experimental Methods for Engineers, McGraw Hill Int., New York
- 2. Venkatesh, V.C., and Chandrasekharan, Experimental Methods in Metal Cutting, Prentice Hall of India, Delhi

- 1. Davis, O.V.; The Design and Analysis of Industrial Experiments, Longman, London
- 2. Box and Jenkins; Time Series analysis, Forecasting and control, Holden Day, Sanfrancisco
- 3. Dove and Adams, Experimental stress analysis and motion measurement, Prentice Hall of India, Delhi
- 4. Tapan P. Bagchi, Taguchi Methods Explained, Prentice Hall of India, Delhi

λM									
M.E. CAD/CAM Maximum Marks									
Total									
100									
nufacturing									
oilities with									
nts									
onents									
ed, flanged									
sa, nangea									
ry									
s 9									
echanisms									
selection, evaluation method, geometrical tolerances, tolerance control and utilization. Economic Use of Raw									
Materials: Ferrous steel, hot rolled steel, cold finished steel, stainless steel, non ferrous materials aluminium,									
copper, brass, non metallic materials, plastics, rubber and composites									
s 9									
and wire									
rts, power									
nd holes,									
s 9									
parts, blow									
saito, sion									
s 9									
y, bearing									
s 9									
s, centred									
ng, group									
technology, low cost automation, computer aided manufacture, product design requirements.									
rs 45									
1. James G. Bralla, — Hand book of product design for manufacturing McGraw Hill Co., 1986 2. K.G. Swift — Knowledge based design for Manufacture II, Kogan page Limited, 1987.									

		ı				1				
CBIT	Autonomous Regulation			nester-1			AY - 200			
Department	Mechanical Engineering			ode & Na			M.E. CAD)/CAM		
Course Code	Course Name	Hours	/ Week		Credit	Maximu	ım Marks			
16MEE 114	DATA BASE	L	Т	Р	С	Е	I	To	tal	
	MANAGEMENT SYSTEMS	3	0	0	3	70	30	10	00	
Objective (s)	1. To understand the differ	rent issu	ies imple	mentation	of a datab	ase syster	n.			
	2. To study the logical data	abase de	esigns, da	tabase mo	deling, rela	ational ne	twork mode	els		
	3. To understand data mar	nipulatio	on langua	ge to quei	ry and man	age a data	abase			
Outcome (s)	After the completion of the cou	urse, th	e studen	t will be a	able to :					
	1. Understand the basic co	oncepts	and appl	ications of	f database s	systems.				
	2. Familiarized with com	mercial	relationa	ıl database	e system.					
	Demonstrate an under	rstandir	ng of the	relationa	l data mod	del				
	4. Familiarized with indexing	ng meth	ods inclu	iding B-tre	e, and hash	ning.				
	5. work successfully in a team by design and development of a database application									
	6. Understand the basics o	f query	evaluatio	n techniq	ues and an	d query or	otimization			
1.							Total		9	
	and E.R. Model: Purpose of dat									
	BA. Entities and entity sets. Rela		ps and r	elationsh	ip sets Ma	pping co	nstraints, F	Primary	Keys	
	, reducing E-R Diagram to tables	3.					1=			
2.			21 1				Total		9	
	odel and relational database de									
normalization.	query languages. Modifying th	e uala	ibase vi	ews. Fit	ialis III le	Hallonai	ualabase	uesign	anu	
3.							Total	Hrs	9	
	nodel and hierarchical data mode	el: data	structure	e diagram	n. the DBT	CCODAS				
	processing facility, Three structi									
4.	, , , , , , , , , , , , , , , , , , ,						Total		9	
File and System	n Structure, Indexing and Hashir	ng: Phy	sical sto	rage med	dia – file o	rganizatio	on, buffer n	nanage	ment,	
Mapping relation	ons, networks and hierarchies to	files – I	ndex – s	sequentia	l files. Bi-tı	ree index	ed files			
5.							Total	Hrs	9	
	abase, security and integrity: [
concurrency co	ntrol, deadlock handling and coo	ordinato	r selecti							
				To	tal hours t	o be taug	ght Tota	l Hrs	45	
Text book (s)										

- 1. Korth, H.F. Silbenhatz, A., Database Concepts, Mc Graw Hill, 1986
- 2. Gio Wiederhold, Database Design, Mc Graw Hill, 1983

- Jefferey O Ullman, Principles of database systems
 C.J. Date, An Introduction to database systems, Addison Wisely, 1980.
 Trembley and Soreson, An Introduction to Data structures with applications, Mc Graw Hills.

CBIT	Autonomous Regulation	Semester-1					AY - 2006-17			
Department	Mechanical Engineering	Progra	amme C	ode & Na	ame		M.E. CAD			
Course Code	Course Name		/ Week		Credit	Maximu	ım Marks			
16MEE 115	FRACTURE MECHANICS	L	Т	Р	С	Е	1	Tot	tal	
		3	0	0	3	70	30	10	0	
Objective (s)	1. To introduce students to	the co	ncepts of	materials	fracture ar	nd failure	analysis			
	To equip them with kno	wledge	on how t	o design a	gainst cata	strophic f	ailures			
Outcome (s)	At the completion of the cours									
	 Identify and explain th 	ne types	s of frac	tures of	engineered	l materia	ls and the	ir charac	teristic	
	features;									
	Understand the differer					•		•		
	their corresponding par					condition	s under wh	nich engin	ieering	
	materials will be liable t		-	-						
		derstand and explain the mechanisms of fracture;								
		the theoretical basis of the experimental techniques utilized for fracture ertise on the experimental techniques utilized for fracture and failure analysis								
	· · ·	•		•				•		
	6. Learn simple LEFM testi	ng meth	ods for e	valuating	the fracture	e toughne				
1.	rock in a Structura Criffth Co	ritorion	Cloov	aga fract	uro Duo	tilo front	Total		9 king	
Introduction: Crack in a Structure – Griffth Criterion – Cleavage fracture – Ductile fracture – Fatigue Cracking. Service failure analysis.										
2. Total Hrs 9										
Elastic Crack: Elastic Crack tip stress field – Solution to crack problems. Effect of finite size stress intensity factor										
	s – Irwin plastic zone correction									
3.	·						Total		9	
	e: Energy release rate – Criteri	on for	crack gr	owth - C	rack resis	tance cu	rve – Prin	ciples of	crack	
arrest - Crack a										
	Growth: Fatigue crack growth to		ess inter	sity facto	or, factors	affecting	stress int	ensity fa	ictor –	
	de service loading, retardation	model	 				T-4-1	I I I I I		
4.	ractura Machanica, Floatia plas	atio from	turo con	cont C	rook tip or	onina di	Total		9	
	racture Mechanics: Elastic plas rmination of J-using FEM	suc mac	ture con	сері – С	rack lip of	bening as	spiacemer	ıı — J-irii	egrai	
	initiation of a doing t Ewi		,				Total	Hrs	9	
	racture Mechanics: Fracture d	esian –	Selecti	on of ma	terials - f	atique cr				
		_				3	3 -			
-				To	tal hours t	o be tauç	ght Tota	al Hrs	45	
Text book (s)										
							al Publish	ers – 197	78.	
	The Analysis of Laminated Co	mposite	e Structu	<i>ıres,</i> Var	n Nostrand	, 1969				
	yo and Jaan Lauis Chhasha Mar	obonico	of Colid	Motorial	o Combrio	lao I Iniva	roity Droo	o Combr	idao	
1007										

CBIT	Autonomous Regulation	Semester-1 AY - 200						06-17		
Department	Mechanical Engineering	Programme Code & Name M.E. CAD/CAM					D/CAM			
Course Code	Course Name	Hours/ Week Credit Maximum Marks								
16MEE 116	DESIGN OF PRESS	L T P C E I								
	TOOLS	3	0	0	3	70	30	100		
Objective (s)	2. To make students ca	 To make the students understand the basic concepts involved in designing press tools To make students capable of designing various press tools which are safe, easy to operate, reliable and economical for manufacturing. 								
Outcome (s)	Student will be able to 1. classify types of press 2. understand the termin 3. understand Elements 4. understand the basic of the basic	ology ir of shea concept epender y	the des ring dies s and pr ntly design	sign of Die inciple in gn various	es. volved in c	lesigning				

1. Total Hrs 9

Classification of Mechanical, Hydraulic, and pneumatic presses, Press Characteristics, safety devices in presses. Principles of stretch forming machines, principles of feeding and unloading equipment. Design principles of presses.

2. Total Hrs 9

Design of Dies: Introduction terminology shearing dies- types of dies – analysis process shearing clearance – size and tolerances of die opening and punch – force, power, energy in shearing – loading center, shearing with inclined edges – strip layouts, economical stock – Utilization.

3. Total Hrs 9

Elements of shearing dies – die plates – split dies, rules of development for split dies, inserts, types of punches, punch holders, punches – strippers – calculation of springs and rubber ejector, shedders, stops

pilots – stock guides – alignment system design for press tools

4. Compound dies, progressive dies, stock feeding devices – cam actuated die, horn dies (type, sub-press dies) – precision shearing dies, shaving dies, lamination dies – Bending dies, theory of bending development of blank,

precision shearing dies, shaving dies, lamination dies – Bending dies, theory of bending development of blank, spring back, curling, flanging and press brake dies, bending on press brake

5. Total Hrs 9

Drawing and forming Dies: Theory of drawing, blank development, strain factor, calculation of force, construction of drawing and drawing dies – Drawing of rectangular components (development, stages draw beeds) – Ironing (application of rubber and hydraulic system) – Defects in deep drawing – Modern Metal forming techniques – Discussion of various computer software for sheet metal design

Total hours to be taught | Total Hrs | 45

Text book (s)

- 1. Fundamentals of tool Design ASTME, Prentice Hall, New Delhi, 1987
- 2. Die design Hand book AISME, Mc Graw Hills, New York, 1965

- 1. Heinrich Makelt, Mechanical Presses, Edward Arnold, London, 1968
- 2. Serope Kalpakjain, Mechanical Processing in Materials, 1967
- 3. Javoronkov V.A and Chaturvedi. R.C. Rolling of Metals
- 4. Eary and Redds, Shear Working of Metals, Prentice Hall, New Delhi, 1969.
- 5. Honeyeeme R.W.K., The plastic Deformation of metals, Edward Arnold, London, 1968
- 6. Kamenschikov, Forging Practice, Mir. Pub., Moscow, 1968
- 7. High Velocity Forming of metals, ASME, Michigan, 1968
- 8. Bhattacharya.A, New Technology, Institute of Engineers, Calcutta, 1973

CBIT	Autonomous Regulation	Semester-1					AY - 2006-17			
Department	Mechanical Engineering	Programme Code & Name					M.E. CAD	D/CAM		
Course Code	Course Name	Hours/ Week Credit			Maximu	ım Marks				
16MEE 117		L	Т	Р	С	Е	I	Total		
	DESIGN OF DIES	3	0	0	3	70	30	100		
Objective (s)	manufacturing dies	2. To make students capable of solving complex geometric problems related to tool and die								
Outcome (s)	1. Apply contemporary design 2. Assess the performance of a 3. Evaluate the effects of a give 4. Describe the principles of cla 5. Design fixtures for milling, be tools for NC machine tools 6. Explain the principles of dies	principle a given en tool amping oring, la	les wher tool des design d , drill jigs athe, grii	designir ign based on the quas and con nding, we	ng advance d on the de ality of the nputer aide	esign crite work. ed jig des	eria; sign			

1. Total Hrs 9

Design principles for dies of thermo-plastic and thermo-setting components. Impression core cavities, strength of cavities, guide pillars and bushes, ejection systems, cooling methods, bolster types. Split moulds, methods of actuating the splits, moulds of threaded components, internal & external under cuts, moulds with under – feed systems. Design principles and standards for Transfer and compression moulding dies.

Design of Tools: Mould for a spindle component with sleeve, pin ejection. Mould with splits Multi-cavity mould with stripper plate, inserts, ejectors.

2. Total Hrs 9

Design of Dies for metal mould Castings, Die casting, Shell moulding.

Design of casting cavity, sprue, slug, fixed and movable cores, finger cam, core, pin, draft, ejector pins, ejector plate, gate, goose-neck, nozzle, over-flow, platen plunger, runner, slot, slide, vent, water line. Design of hot chamber, cold chamber machines, vertical, horizontal,, die locking machines, toggle and hydraulic systems, injection systems, rack and pinion, knockout pins and plates, hydraulic ejection, Other parts of die casting machines

3. Total Hrs 9

Design of various types of dies – Single cavity, multi cavity, combination, unit dies. Alignment of dies with sprue. Design approach for die elements. Selection of materials and heat treatment for die casting dies and elements – die casting alloys – types of die casting alloys, Case studies on executed dies and design details. Finishing, Trimming, and inspection. Gravity die casting – Die design with cores and inserts – Bulk forming tools

4. Total Hrs 9

Open die forging, Advantages of open die forging over closed die forging. Calculation of allowances and tolerances. Methods of open die forging. Design of dies. Closed die forging. Preparation of material for forging. Calculation of raw-stock, cutting off, heating in furnaces. Allowances and tolerances for closed die forging as per IS: 3469 1974

5. Total Hrs 9

Die blocks for forging operations. Design of fuller impression, Roller impression, Bender impression, Blocker impression, Finisher impression. Swaging tools. Planning layout of multi impression dies. Flash and cutter calculations – additional operations on forging, piercing, and trimming dies, coining dies. Horizontal forging machines. Design of upsetting dies. Calculations on upsetting dies – Press forging reducer rollers. Forging equipment. Layout of forge shop. Roll forming, wire drawing forward & backward extrusion

Total hours to be taught Total Hrs 45

Text book (s)

- 1. Rusinoff S.E., Forging & Forming Metals, Taraporewala, Bombay, 1952
- 2. Dochlar H.H., Die Casting Dies, Mc Grawhill, 1951

- 1. I.S. Standards, BSI., New Delhi.
- 2. Pye R.G.W., Injection Mould Design, Longman scientific & Technical Publishers, London, 1989

Mechanical Engineering Course Name RAPID PROTOTYPING PRINCIPLES AND APPLICATIONS	Hours L	amme C / Week T	ode & Na P	Credit	Maximu	M.E. CAD ım Marks	D/CAM
RAPID PROTOTYPING PRINCIPLES AND	L	/ Week T	D		Maximu	ım Marks	
PRINCIPLES AND	L	Т	D	_			
	_		Г	С	Ε	_	Total
	3	0	0	3	70	30	100
 To make students technologies. To understand and apapplication. 	understand the basic concepts of various rapid prototyping						
used RP systems 2. describe various CAD model generation and 3. Explain and summarize plastic and metal parts 4. critically explore tech parameters, applications	I manipulation ze typical rapid tooling processes for quick batch production of s chnologies used for rapid prototyping in terms of their ion, limitations, cost, materials, equipment, outcomes and						
	used RP systems 2. describe various CAD model generation and 3. Explain and summariz plastic and metal parts 4. critically explore tect parameters, applications	used RP systems 2. describe various CAD issues model generation and manipu 3. Explain and summarize typica plastic and metal parts 4. critically explore technologi parameters, application, limimplications	used RP systems 2. describe various CAD issues for rap model generation and manipulation 3. Explain and summarize typical rapid to plastic and metal parts 4. critically explore technologies used parameters, application, limitations, implications	used RP systems 2. describe various CAD issues for rapid prototy model generation and manipulation 3. Explain and summarize typical rapid tooling proplastic and metal parts 4. critically explore technologies used for raparameters, application, limitations, cost, mimplications	used RP systems 2. describe various CAD issues for rapid prototyping and model generation and manipulation 3. Explain and summarize typical rapid tooling processes for plastic and metal parts 4. critically explore technologies used for rapid protor parameters, application, limitations, cost, materials, elimplications	used RP systems 2. describe various CAD issues for rapid prototyping and related of model generation and manipulation 3. Explain and summarize typical rapid tooling processes for quick be plastic and metal parts 4. critically explore technologies used for rapid prototyping in parameters, application, limitations, cost, materials, equipmer implications	 used RP systems describe various CAD issues for rapid prototyping and related operations model generation and manipulation Explain and summarize typical rapid tooling processes for quick batch produplastic and metal parts critically explore technologies used for rapid prototyping in terms parameters, application, limitations, cost, materials, equipment, outcomimplications

1. | Total Hrs | 9 | Introduction: Prototyping fundamentals, Historical development, Fundamentals of Rapid Prototyping,

Advantages and Limitations of Rapid Prototyping, Commonly used Terms, Classification of RP process, Rapid Prototyping Process Chain: Fundamental Automated Processes, Process Chain

Liquid-based Rapid Prototyping Systems: Stereo lithography Apparatus (SLA): Models and specifications, Process, working principle, photopolymers, photo polymerization, Layering technology, laser and laser scanning, Applications, Advantages and Disadvantages, Case studies. Solid ground curing (SGC): Models and specifications, Process, working principle, Applications, Advantages and Disadvantages, Case studies Solid-based Rapid Prototyping Systems: Laminated Object Manufacturing (LOM): Models and specifications, Process, working principle, Applications, Advantages and Disadvantages, Case studies. Fused Deposition Modeling (FDM): Models and specifications, Process, working principle, Applications, Advantages and Disadvantages, Case studies.

3. Total Hrs 9
Powder Based Rapid Prototyping Systems: Selective laser sintering (SLS): Models and specifications,

Provider Based Rapid Prototyping Systems: Selective laser sintering (SLS): Models and specifications, Process, working principle, Applications, Advantages and Disadvantages, Case studies. Three dimensional Printing (3DP): Models and specifications, Process, working principle, Applications, Advantages and Disadvantages, Case studies.

Rapid Tooling: Introduction to Rapid Tooling (RT), Conventional Tooling Vs RT, Need for RT. Rapid Tooling Classification: Indirect Rapid Tooling Methods: Spray Metal Deposition, RTV Epoxy Tools, Ceramic tools, Investment Casting, Spin Casting, Die casting, Sand Casting, 3D Keltool process. Direct Rapid Tooling: Direct AIM, LOM Tools, DTM Rapid Tool Process, EOS Direct Tool Process and Direct Metal Tooling using 3DP

4. Total Hrs 9

Rapid Prototyping Data Formats: STL Format, STL File Problems, Consequence of Building Valid and Invalid Tessellated Models, STL file Repairs: Generic Solution, Other Translators, Newly Proposed Formats. **Rapid Prototyping Software's:** Features of various RP software's like Magics, Mimics, Solid View, View Expert.

3 D View, Velocity 2, Rhino, STL View 3 Data Expert and 3D doctor

5. Total Hrs 9

RP Applications: Application – Material Relationship, Application in Design, Application in Engineering, Analysis and Planning, Aerospace Industry, Automotive Industry, Jewelry Industry, Coin Industry, GIS application, Arts and Architecture. **RP Medical and Bioengineering Applications:** Planning and simulation of complex surgery, Customised Implants & Prosthesis, Design and Production of Medical Devices, Forensic Science and Anthropology, Visulization of Biomolecules

Total hours to be taught | Total Hrs | 45

Text book (s)

- 1. Rapid prototyping: Principles and Applications Chua C.K., Leong K.F. and LIM C.S, World Scientific publications , Third Edition, 2010
- 2. Rapid Manufacturing D.T. Pham and S.S. Dimov, Springer, 2001

- 1. Wholers Report 2000 Terry Wohlers, Wohlers Associates, 2000
- 2. Rapid Prototyping & Manufacturing Paul F. Jacobs, ASME Press, 1996

CBIT	Autonomous Regulation		Sen	nester-1		AY - 2006-17				
Department	Mechanical Engineering	Progr	amme C	ode & Na	ame		M.E. CAD	D/CAM		
Course Code	Course Name	Hours/ Week Cre			Credit	Maximum Marks				
16MEE 119	Flexible Manufacturing	L	Т	Р	С	Е	I	Total		
	Systems	3	0	0	3	70	30	100		
Objective (s)	methods. The fundamentals of concepts that include usage of removal, washing station, fixtu	course covers the significance of manufacturing systems over numerical control machining ods. The fundamentals of flexible manufacturing system are clearly stated from the design epts that include usage of operation cycle description, robot automatic guided vehicle, chip wal, washing station, fixturing etc								
Outcome (s)	Upon completion of the subject 1. the understand the elect 2. Students can independ be performed for mar 3. understand the function 4. understand Automated 5. understand the concept 6. understand the FMS described in the subject 1.	ements ndently nufactu ioning d storag ot of jus	of flexible developering of soft prograge and rest in time	e manufa o the sec a produc ammable etrieval sy	quence of t logical co stems	operation	ons that a	are to		

1.Total Hrs9Evolution of Manufacturing Systems: FMS definition and description, General FMS considerations,

Manufacturing Systems: FMS definition and description, General FMS considerations, Manufacturing cells, Cellular versus Flexible Manufacturing.

Systems Planning: Objective, introduction planning, preparation guidelines, the project team, supplier selection,

systems Planning: Objective, introduction planning, preparation guidelines, the project team, supplier selection, system description and sizing, facility preparation planning, FMS layouts. Human resources: staff considerations, team work, communication and involvement, the supervisors role, personnel selection, job classifications, employee training

2. Total Hrs 9

Manufacturing's Driving Force: Definition, description and characteristics. Just in-time manufacturing, definition and description, benefits and relationship to FMS, implementation cornerstones, quality and quantity application principles. Single manufacture Cell – design scheduling of jobs on single manufacturing cells.

Group Technology: Concepts, classification and coding, benefits and relationship to FMS, design of group technology using rank order clustering technique

3. Total Hrs 9

FMS Design – Using Bottleneck, Extended bottleneck models, Processing and Quality Assurance: Turning centres, Machining centre, construction and operations performed, axes, programming, and format information, workholding and work-changing equipment, automated features and capabilities, cleaning and deburring – station types and operation description, importance to automated manufacturing, coordinate measuring machines, types, construction and general function, operation cycle description, importance to flexible cells and systems

4. Total Hrs 9

Automated movement and storage systems–AGVs, Robots, automated storage and retrieval systems, storage space design, queuing carousels and automatic work changers, coolant and chip Disposal and recovery systems, auxiliary support equipment, cutting tools and tool Management – introduction, getting control of cutting tools, Tool Management, tool strategies, data transfer, tool monitoring and fault detection, guidelines, work holding considerations, General fixturing, Modular fixturing. FMS and the relationship with workstations – Manual, automated and transfer lines design aspects

5. Total Hrs 9

FMS: computer Hardware, Software, Communications networks and Nanotechnology – general functions, and manufacturing usages, hardware configuration, programmable logic controllers, cell controllers, communications networks. FMS implementation

Total hours to be taught | Total Hrs | 45

Text book (s)

- 1. Parrish, D.J., _Flexible Manufacturing', Butter Worths Heinemann, Oxford, 1993
- 2. Groover, M.P., Automation, Production Systems and CIM, Prentice Hall India, 1989

- 1. Kusiak, A., Intelligent Manufacturing Systems', Prentice Hall, 1990
- 2. Considine, D.M., & Considine, G.D., Standard Handbook of Industrial Automation, -Chapman & Hall, 1986
- 3. Ranky, P.G., _Design and Operation of FMS', IFS Publishers, UK, 1988

CBIT	Autonomous Regulation	Semester-1 AY - 2006-17							
Department	Mechanical Engineering	Programme Code & Name M.E. CAD/CAM							
Course Code	Course Name	Hours	/ Week		ım Marks				
16MEE 120	NON-TRADITIONAL	L T P C E					ı	To	tal
	MACHINING AND FORMING	3	0	0	3	70	30	10	00
Objective (s)	 To make the students understand the need and the applications of nontraditional machining processes. To choose the NTM processes for particular applications 								
Outcome (s)	2.the processes of Thermal Me 3.the parameters and chemistr 4.the principles of Plasma Arc 5.the principles of laser Beam								
1.	N. 16 (197)						Total	Hrs	9

Introduction: Need for non-traditional machining processes. Processes selection, classification, comparative study of different processes.

Mechanical Process: Ultrasonic Machining-Definition-Mechanism of metal elements of the process- Tool feed mechanism. Theories of mechanics of causing effect of parameter applications.

Abrasive Jet Machining: Principles - parameters of the process, applications, advantages and disadvantages.

Water Jet Machining (WJM): Schematic diagram, equipment used, advantages and applications

Thermal Metal Removal Process: Electric discharge machining Principle and operation – mechanism of meta removal, basic EDM circuitry-spark erosion. Analysis of relaxation type of circuit material removal rate in relaxation circuits- critical resistance parameters in Ro Circuit-Die electric fluids- Electrodes for surface finish. Applications. Wire EDM principle and operation. Wire materials, wire tension and its parameters. Applications

3. Total Hrs 9

Electro Chemical and Chemical Processes: Electro chemical machining (ECM) Classification ECM process-principle of ECM Chemistry of the ECM parameters of the processes-determination of the metal removal rate - dynamics of ECM process-Hydrodynamics of ECM process-polarization. Tool Design-advantages and disadvantages - applications. Electro Chemical Grinding-Electro Chemical holding Electrochemical deburring.

Plasma Arc Machining: Introduction-Plasma-Generation of Plasma and equipment Mechanism of metals removal, PAN parameters-process characteristics - type of torches applications

4. Total Hrs 9

Electron Beam Machining (EBM): Introduction-Equipment for production of Electron beam - Theory of electron beam machining Thermal & Non thermal types characteristics – applications.

Laser Beam Machining (LBM): Introduction-principle of generation of lasers Equipment and Machining procedure-Types of Lasers-Process characteristics-advantages and limitations-applications

5. Total Hrs 9

High Velocity Forming Process: introduction - development of specific process selection-comparison of conventional and high velocity forming methods - Types of high velocity forming methods- explosion forming

process-elector hydraulics forming magnetic pulse forming. Electro-Magnetic Forming. Rubber Pad Forming: Principle of the process, process details, process variants - Guerin, wheelon, Marforming and Hydro forming processes and applications

Total hours to be taught | Total Hrs | 45

Text book (s)

- 1. New Technology Institution of Engineers Bhattacharya India
- 2. Production Technology HMT Tata Mc Graw Hill ISBN-10

- 1. Modern Manufacturing Method Adithan New Age International (p) Limited
- 2. Modern Machining Processes P.K. Mishra Narosa Publishing House, New Delhi 1997.

CBIT	Autonomous Regulation	Semester-1 A						06-17			
Department	Mechanical Engineering	Progr	amme C	ode & Na	M.E. CAD/CAM						
Course Code	Course Name		s/ Week		num Marks						
16MEE 121	PRODUCT DESIGN AND	L	Т	Р	С	Е		Tota	I		
	PROCESS PLANNING	3	0	0	3	70	30	100			
Objective (s)		out design and manufacturing engineering mic considerations to manufacture a product									
Outcome (s)											
6 .Mechanical engineering solutions to green and sustainable development Total Hrs 9											
procedure-Flo of appearance	f design, sources of new ideas w chart. Qualifications of produ e, colours and Laws of appearan	ct desig					ure of a p	roduct. Va	alue		
2.	_						Total		9		
Definitions, cla products, Elen analysis, Brea Procedures of	ility, Mortality Curve, Reliability s asses of patents, applying for pa nents of cost of a product, costir k even analysis Charts. Value e value analysis – cost reduction,	itents. T ng meth nginee	rademai ods, cos ring in pr	ks and c t reduction duct des	opyrights. on and cos sign, crea	Cost and st control	I quality se activities. ects and te	ensitivity of Economic chniques.			
3.							Total		9		
improving toler Physical prope	Various manufacturing processes, degree of accuracy and finish obtainable, process capability studies. Methods of improving tolerances. Basic product design rules for Casting, Forging, Machining, Sheet metal and Welding. Physical properties of engineering materials and their importance on products. Selection of plastics, rubber and ceramics for product design										
4.							Total		9		
design-Anthro importance, A	Industrial ergonomics: Man-machine considerations, ease of maintenance. Ergonomic considerations in product design-Anthropometry, Design of controls, man-machine information exchange. Process sheet detail and their importance, Advanced techniques for higher productivity. Just-in-time and Kanban System. Modern approaches to product design; quality function development, Rapid prototyping										
5.							Total		9		
Role of compu	ter in product design and mar	nageme	ant of m	anufactuu	ring crea	tion of m	anufacturi	na data h	1266		

Role of computer in product design and management of manufacturing, creation of manufacturing data base, Computer Integrated Manufacturing, communication network, production flow analysis, Group Technology, Computer Aided product design and process. Planning. Integrating product design, manufacture and production control

Total hours to be taught | Total Hrs | 45

Text book (s)

- Niebel, B.W., and Draper, A.B., Product design and process Engineering, Mc Graw Hill Kogalkusha Ltd., Tokyo, 1974.
- 2 Chitale, A.K, and Gupta, R.C., Product Design and Manufacturing, Prentice Hall of India Pvt. Ltd., New Delhi, 2004

Reference(s)

1. Mahajan, M. Industrial Engineering and Production Management, Dhanpath Rai & Co., 2000

CBIT	Autonomous Regulation	Semester-1				AY - 2006-17		
Department	Mechanical Engineering	Programme Code & Name					M.E. CAD	D/CAM
Course Code	Course Name	Hours/ Week Cree			Credit	Maximu	ım Marks	
		L	Т	Р	С	E	1	Total
16MEC 106	CAD/CAM LABORATORY	0	0	3	2		50	50

Objective(s):

- 1. To produce CAD drawings which communicate the appropriate manufacturing details, standards, and specifications..
- 2. To effectively communicate with others using oral, written, and graphical methods and procedures..
- 3. To function effectively on teams or on group projects and assume leadership roles when appropriate..
 - To introduce STUDENTS to the basic tools of computer-aided design (CAD) and computer-aided manufacturing (CAM)
 - To understand the basic analytical fundamentals that are used to create and manipulate geometric models in a computer program
 - 6 To prepare the student to be an effective user of a CAD/CAM system.

Outcome(s): After the completion of the course, students will be able to

- 1. use parametric CAD software for geometric modeling of mechanical designs
- 2. visualize of machine components and assemblies before their actual fabrication through modeling, animation, shading, rendering, lighting and coloring
- 3. apply of CAD computational analysis tools to engineering design.
- 4. create a complete CAD documentation for an engineering design.
- 5. model complex shapes including freeform curves and surfacesExplain the basic concepts of CNC programming and machining
- 6. implement CNC programs for milling and turning machining operations

List of Exercises:

CAD

- 1. Understanding of various CAD commands and creating simple objects.
- 2. Understanding of holes, cuts and model tree relations.
- 3. Creation shafts, rounds, chamfers and slots.
- 4. Sketch Tools & Datum planes.
- 5. Creation of objects by revolved features, patterns and copies, sweeps and blends.
- 6. Creation of engineering drawing details such as dimensioning, sectional views, adding esthetics.
- 7. Assembling of part models using constraints with bill of materials.
- 8. Assembly operations part modifications, adding another assembly features display.
- 9. Mass properties and tolerance analysis.

CAM

- Understanding of CNC Machines and CNC Programming and Creation of 2-D contour Pockets, Slots
- 2. Drills and Facing, 2-D high Speed blend
- 3. Surface Roughing for Bottle die
- 4. Surface finishing for Phone die
- 5. Manufacturing of Crane Hook
- 6. Manufacturing of Connecting Rod
- 7. Manufacturing of Turbine Blade
- 8. 3-D Machining using ball nose cutters

CBIT	Autonomous Regulation	Semester-1				AY - 2006-17		
Department	Mechanical Engineering	Programme Code & Name					M.E. CAD)/CAM
Course Code	Course Name	Hours/ Week Cre			Credit	Maximum Marks		
	COMPUTATIONAL	L T P			С	E	1	Total
16MEC 107	LABORATORY	0	0 0 3 2				50	50

Objective(s)

- 1. To understand how and why finite element technique works
- 2. To learn the selection of the element type for a defined problem.
- 3. To use ANSYS package to solve engineering problems for a variety of application
- 4. To learn to use finite element analysis in design
- 5. To know various fields of engineering where these tools can be effectively used to improve the output of a product
- 6. To impart the fundamental knowledge on using various analytical tools like ANSYS Engineering Simulation.

Outcome(s):

Students will be able to:

- 1. Use the tools like ANSYS in solving real time problems and day to day problems.
- 2. Apply the Finite Element Method for the calculation stresses, strains and deformations in any component
- 3. critically evaluate the model results in comparison to simplified analytical solutions
- 4. Versatility in using these tools for any engineering and real time applications.
- 5. Gain knowledge on utilizing these tools for a better project in their curriculum
- 6. Face industry with confidence in using these tools in their respective jobs

List of Experiments:

- 1. Introduction to Finite Element Analysis Software.
- 2. Static analysis of a corner bracket.
- 3. Statically indeterminate reaction force analysis.
- 4. Determination of Beam stresses and Deflection.
- 5. Bending analysis of a Tee-shaped beam.
- 6. Analysis of cylindrical shell under pressure.
- 7. Bending of a circular plate using axisymmetric shell element.
- 8. Stress analysis in a long cylinder.
- 9. Solidification of a casting.
- 10. Transient Heat transfer in an infinite slab.
- 11. Transient Thermal stress in a cylinder.
- 12. Vibration analysis of a simply supported beam.
- 13. Natural frequency of a motor generator.
- 14. Thermal structural contact analysis of two bodies.
- 15. Drop test of a container (Explicit Dynamics).

16MEC 110

MINIPROJECT GUIDELINES

Instruction	2 Hrs / week
Sessional	50 Marks
Credits	01

Objectives:

First year ME students will each do a 14-week mini project, each generally comprising about one week of prior reading, twelve weeks of active research, and finally a presentation of their work for assessment (see assessment information below). Each student will be allotted to a Faculty supervisor for mentoring.

Mini projects should present students with an accessible challenge on which to demonstrate competence in research techniques, plus the opportunity to contribute something more original. Mini projects should have inter disciplinary/ industry relevance. The students can select a mathematical modeling based/Experimental investigations or Numerical modeling. All the investigations are clearly stated and documented with the reasons/explanations. All the projects should contain A clear statement of the research objectives, background of work, Literature review, techniques used, prospective deliverables, benefit from this [line of] research, Detailed discussion on results, Conclusions and references.

Outcomes:

Students are able to

- 1. Formulate a specific problem and give solution
- 2. Develop model/models either theoretical/practical/numerical form
- 3. Solve, interpret/correlate the results and discussions
- 4. Conclude the results obtained and write the documentation in standard format

Assessment:

1. 50 % of marks for a scientific report on the project.

Regarding the formatting and structure, the report should be written as a journal article using the style file of a journal appropriate for the field of the research (which journal format is most appropriate should be agreed between student and supervisor). If the journal you selected has a page limit, it can be ignored but the report should not exceed 8000 words (common sense should be used if there are a lot of equations).

Regarding content, the report should be understandable by your fellow students, so the introduction and literature review could be a bit more detailed than in a research paper. The results and discussions are in elaborate form and at end conclusions and include references.

2. 50 % of marks for an oral presentation which will take place at the end of the semester and evaluation by a committee consist of Supervisor, one senior faculty and Head of the department or his nominee.

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